FLEXDRUM

User Manual



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| Declaration | of conformity |
|-------------|---------------|
|-------------|---------------|

| The product: | |
|----------------------|--|
| Model no: | |
| Serial no: | |
| Year of manufacture: | |

Described in the enclosed documentation is in conformity with:

- Directive 2006/42/CE of 29 December replacing the Directive 98/37/EC of 22 June 1998 relating to the approximation of the laws of the Member States relating to machinery, combining in a single text Directives 89/392/EEC of 14 June 1989, 91/368/EEC of 20 June 1991, 93/44/EEC of June 14, 1993 and 93/68/EEC of 22 July 1993. Directive used law EN ISO 12100-1 and EN ISO 12100-2, relative to safety of the machines, law EN ISO 14121-1, relative Safety of the machines. Evaluate of risk, law UNE-EN 60204-1, relative to Safety of machines. Electric equipment of the machines, law UNE-EN 61310-1, UNE-EN 61310-2 y UNE –EN 61310-3, relative to Safety in machines. Indication, marking and actuation.
- Directive 2014/35/UE of April, relating to electric equipment.
- Directive 2014/30/UE of April, relating to electromagnetic compatibility.
- Directive 93/68/EEC of 22 July 1993, amending Directive 73/23/EEC, and Directive 89/336/EEC.

within the scope of the specifications indicated in the chapter describing the equipment with a B1 risk level. Since it is intended to form part of a set of machines which, to obtain a result, are arranged and connected to perform together, it cannot be operated until the set of machines has been declared in conformity with the applicable Directives by the person responsible for the final assembly.

Orcoyen, on : / /

Signed:

Gonzalo Marco, Managing Director.



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IMPORTANT!

THIS INSTRUCTION MANUAL SHOULD BE KEPT IN AN ACCESSIBLE PLACE KNOWN TO ALL OPERATORS AND MAINTENANCE PERSONNEL.

READ THE INSTRUCTIONS CAREFULLY BEFORE OPERATING THE MACHINE AND FOLLOW THEM WHILE THE MACHINE IS IN OPERATION.

FOLLOW THE SAFETY INSTRUCTIONS PROVIDED IN THIS MANUAL WHEN USING AND HANDLING THE MACHINE.

IF YOU FAIL TO FOLLOW THE SAFETY INSTRUCTIONS, THIS MAY GIVE RISE TO BURNS, INJURIES AND EVEN IRREVERSIBLE DAMAGE. YOU MAY ALSO DAMAGE THE EQUIPMENT OR OTHER MATERIALS.

WARNING:

If you alter the function, performance or safety aspects of the machine, replacing original parts with other similar but not identical components (substantial alterations), without the authorisation of MELTON and as specified in Directive 89/392/EEC, you will be classified as a manufacturer and therefore become liable for the alterations made.



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CHAPTER 1 SAFETY INSTRUCTIONS

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1.1. SYMBOLS AND TERMS:



Precaution: risk of entrapment between mobile parts



Note of special interest



Use of goggles required



Use of safety gloves required



Burns:



Burns can be caused by the uncovered parts of the applicator, such as the guns or by splashes of hot melt.

The hot adhesive under pressure in the nozzles can cause serious injuries to the skin.

Qualified personnel:

This is personnel (technical staff) who has acquired sufficient know-how in a specific field, either through training or from experience.

These personnel must be familiar with safety and accident prevention standards, and have general knowledge of the technical aspects of the machine.

Protective clothing:

This clothing will be compliant with EN510 and EN340 standards, protecting against fast-moving particles and high temperatures.

It will be as tight as possible to prevent it from catching on mobile machine parts, and the sleeves, waist, legs, etc. will be adjustable to the size of the wearer.

Goggles and face shields:



They will be compliant with the EN 166 standard, protecting against fastmoving particles and high temperatures.

Goggles only protect the eyes. Face shields are therefore preferable, since they protect the entire face.



Protective gloves:

They will be compliant with EN 407 and EN 420 standards, protecting the hands against the burns caused by external thermal masses at temperatures of above 100 °C.



1.2. PURPOSE:



This unit has been manufactured according to current safety standards.

This unit has been designed for the purpose described in chapter 2 of this manual, Description.

To use the machine correctly, follow the instructions provided in the Operating Manual, particularly:

- The machine should only be installed and used by qualified personnel, previously familiarised with the operating instructions (contacting the manufacturer whenever necessary) and the risks involved, the safety measures required, including adjustment and maintenance, and expressly forbidden operations.
- This unit has not been manufactured to operate in hazardous, explosive and/or flammable atmospheres
- When working with this machine, wear protective clothing, gloves and face shields and remove rings, bracelets and watches.
- Since the machine is designed to form part of a series of machines, arranged to work together, the hot melt applicator cannot be operated until the entire series has been declared in compliance with applicable directives.
- This machine should never work without the guards provided (which should not be removed). These guards should be checked and maintained with the specified frequency.
- > Make sure that the equipment is properly grounded.
- Never operate the machine if you are aware that there is a leak in the glue circuit.
- Maintenance operations and/or repairs should be performed by personnel with basic knowledge of the machine and the mechanical, pneumatic and electric circuits involved.
- Maintenance operations and/or repairs should always be performed with the machine switched off at the mains, and with the main switch blocked.
- Maintenance operations and/or repairs should always be performed with the machine de-pressurised and disconnected from the pressure circuit.





1.3. FIRST AID:

In case of burns:



Immerse affected part in cold clean water as quickly as possible until the adhesive has cooled.

Do not attempt to remove the adhesive from the skin even when it has cooled as this may cause more serious injury.

Seek qualified medical attention immediately.

In case of an accident with the solvent:



CONTACT WITH THE SKIN: Wash with soap and water and discard all contaminated cloths.

CONTACT WITH EYES: Wash in an eye bath for at least 15 minutes.

INHALATION: In case of overexposure take patient to fresh air and let them rest.

INGESTION: Do not attempt to induce vomiting. Seek medical attention at once.



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CHAPTER 2 DESCRIPTION

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2.1. INTRODUCTION:

This machine heats hot-melt adhesive (or similar materials in a drum) until it goes from solid to liquid state in a heated container. A pump absorbs the glue at a certain pressure through heated hoses and transfers it to where it is applied.

2.2. MAIN PARTS:

The main parts of the machine are shown on the following figure:



| N. | DESCRIPCIÓN | | |
|----|------------------|--|--|
| 1 | Motor | | |
| 2 | Pump | | |
| 3 | Manifold | | |
| 4 | Electric cabinet | | |
| 5 | Cylinders | | |
| 6 | Base frame | | |

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2.2.1. Base frame:



The structure consists of a base plate on which pneumatic cylinders are installed. These cylinders raise and lower the melt plate by means of bars.

The drum is secured to this base plate.

2.2.2. Melt plate:

This is the part that melts the hot-melt product. It consists of a cast aluminium plate heated by electric heating elements. This process is controlled by the control board. The melt plate is lowered as the adhesive melts, and keeps the drum sealed, preventing air from entering or hot melt material from leaking.

2.2.3. Pump-distribution system:

It transfers the adhesive from the drum to the distributor.



The pump pushes the hot-melt or other heated product at a certain pressure from the melt system to the hoses and guns.

The pump is located on one side of the melt system and driven by an alternate current geared motor.

Pump speed is shown on the display on the front of the control cabinet.

Manifold:



The distributor carries the hot-melt to the hoses and guns.

It is made out of aluminium, and installed on the bottom of the melt system. It is heated by internal heating elements.

The distributor also contains a filter, a bleed valve, a safety valve regulator,

a distributor crank assembly and a pressure transducer (optional)

Each distributor has 2 hose connection outlets.



Geared motor:

The geared motor controls the pump. It is an alternate current motor controlled by a vector frequency shifter which transmits power through a pump connection.

Motor speed can be adjusted manually or automatically, depending on the power required for the main machine, which should never exceed 80 rpm.



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2.2.4. Electric system:



It consists of one electric cabinet:

Electric cabinet:

At the top it contains all the control and power electronics required for the machine to operate.

2.2.5. Pneumatic system:



It consists of two independent circuits. The first is used to control the vertical movement of the melt plate and the pressure of the melted adhesive to the pump.

The second circuit controls the fill valve that injects air into the drum before the melt plate is removed.

It is situated at the outside electric cabinet.



2.2.6. Control panel:

The control panel containing the machine's operating and adjustment switches is on the front of the electric cabinet.





Two-hand on/off button:

This sets the plate in movement. The two buttons have to be pressed at the same time.



Position selector:

It is for moving the melt plate (downward or upward).

Control Panel:

It lets the user of the unit to control the unit.

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2.3. TECHNICAL SPECIFICATIONS:

| COMPONENT | DATA |
|-------------------------------|---|
| GENERAL | |
| Maximum Power supply | 17000 W |
| Power supply voltage | III 400V+N+T (50-60Hz) |
| Hoses (max.) | 2 |
| Hydraulic pressure | 2.8 – 80 bar (40 – 1138 psi) |
| Noise level | 63 dB |
| Operating temperature | -10°C – 50 °C (32°F – 122°F) HR 20% to 80% not condensed |
| Max. operating viscosity | 90000 cps |
| | |
| CONTROL | |
| Operational programming range | 80° - 230° C (176° - 446° F) |
| Temperature control accuracy | +/- 0.5° C (+/- 1° F) |
| Control type | PID |
| | |
| PUMP | |
| Pumping capacity | 4 - 30 cc/rev |
| | |
| TANK | |
| Volume | 200 L |

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2.4. OVERALL DIMENSIONS OF THE FLEXDRUM UNIT:









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CHAPTER 3 INSTALLATION OF THE MACHINE

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3.1. INTRODUCTION:



This chapter explains how to install the machine correctly.

WARNING: The operations described in this chapter should be performed by qualified personnel, following safety instructions.

3.2. TRANSPORT:

The equipment is supplied palletised with a wooden frame.

Remove the top and front covers to unpack.



Unpack carefully to prevent damage to the machine. Inspect the equipment for damages caused during transport.

3.3 INSTALLATION REQUIREMENTS:

Install the unit leaving enough space for the equipment to be accessed during operations.



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The distances are indicated for the equipment to be handled manually or by lift-truck.

Avoid extreme temperatures (below -10 C and above +50 C).

Try to avoid installing the equipment where there are draughts. If this is not possible, the guns will need protecting because if the temperature falls rapidly, they may not work properly.

3.4. MECHANICAL INSTALLATION:

The mechanical installation includes the following:

- Positioning the equipment.
- > Connecting the hoses.

Positioning the equipment:

Remove from the pallet using a forklift or travelling crane, and position according to installation requirements (chapter 3.3)

Connecting the hoses:

Proceed as follows:



Make sure that the equipment is depressurised before connecting the hose. Set the motor control selector to zero and bleed with bleed valves. Heat the machine to melt any adhesive that may be present.

1º Remove the distributor cap.



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2º Screw on the male-male plug, as per hose diameter.



3º Screw the hose to the plug.



- 4° Connect the machine electrically to the electric panel.
- 5° Insert the hose through the upper spring and install as indicated.
- **6°** When the hose is at the relevant temperature, re-tighten the male-male plugs and the hose.



Hose placement:

Never bend the hoses to angles with a radius of less than 150 mm.



Hoses should not be allowed to lie on cold surfaces such as factory floors.



Do not bunch hoses together. Leave at least a 25 mm gap between them.



Do not cover hoses. If it is necessary to cover your hoses ensure that there are vents to allow heat to be dissipated.



Do not install hoses with clamps smaller that the hoses.





0

YES





3.5. PNEUMATIC INSTALLATION:



Connect the air supply to the pressure adjustment inlet. The minimum pressure required by the equipment is 4 kg.



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The electrical wiring depends on the model. See electrical diagrams.

Make sure the power source is duly protected and you are using the right cable for the machine's electrical power needs.

Secure the power cord to the machine bench in order to prevent an accident.

Connect the pump permissions to the main machine's safety line.



When the machine is connected to a main machine, it won't run until the external permission is given. These terminals are factory shortcircuited

3.7. MAIN MACHINE INTERFACE

For the communication between the melter equipment and the main machine, we will use the next connector.



To make the wiring correctly, see electrical diagrams. Only shielded cable may be connected. Also, this shield must be connected to ground conforming to the European standard regarding electromagnetic compatibility (EMC).

The pinout of this connector is the next.



| Pin | Input/Output | | Function | |
|------|---|-------------|--|--|
| | | | Internal voltage for the activation of the inputs 3,4,5,6,7,8,9,11,12,13 and | |
| | | | 14. | |
| 1 | Output | 24 VDC | Only connect if we want to use voltage connection (we will see it later). | |
| 3 | | | Rising edge: Heat ON | |
| | | | Falling edge: Heat OFF | |
| 4(*) | *) Input 0 VDC 24 V: Pump Enable (Safety 0) 0V: All Pumps Disabled | | 24 V: Pump Enable (Safety Enable) → ALWAYS SHOULD BE CONNECTED 0V: All Pumps Disabled | |
| 9 | Input | | Rising edge: Switch on Standby | |
| | | | Falling edge: Switch off Standby | |
| | | | 24V : Enable Temperature External Input 1 | |
| 11 | Input | | 0V: Temperature External Input 1 | |
| | input | | NOTE: In the touch screen you can choose the function of this temperature | |
| | | | input | |
| | | | 24V : Enable Temperature External Input 2 | |
| 12 | Input | | 0V: Temperature External Input 2 | |
| 12 | | | NOTE: In the touch screen you can choose the function of this temperature | |
| | | | | |
| | | | 24V : Enable Temperature External Input 3 | |
| 13 | Input | lnput | | 0V: Temperature External Input 3 |
| | | | NOTE: In the touch screen you can choose the function of this temperature | |
| | | | 24V : Enable Temperature External Input 4 | |
| 14 | Input | | 0V: Temperature External Input 4 | |
| | | Input | | NOTE: In the touch screen you can choose the function of this temperature |
| | | | input | |
| | | | Customer Reference. ALWAYS SHOULD BE CONNECTED. In this way, | |
| 2 | Input | Input 0 Vdc | FLEXDRUM unit and customer's machine always will have the same | |
| | | | reference. | |

(*) IMPORTANT NOTE



If we work by COMMUNICATIONS, the "Pump enable" signal always should be connected, because it works as SAFE TORQUE OFF input.

Then, you also will enable the pump using the communication register



| Pin | Input/Output | | Function |
|-----|--------------|-------------------------|--|
| 25 | Input | 24 Vdc | External voltage (from main machine) for the activation of the outputs 18,19,20,21,26 and 28. Only connect if we want to use voltage connection (we will see it later). |
| 26 | Output | Make contact | 24V : System Ready 0V: System Not Ready |
| 28 | Output | Brake contact | 24V : System Not Fault 0V: System Fault |
| 20 | Output | | 24V : Drum Low Level 0V: Not Drum Low Level |
| 21 | Output | | 24V : Drum Empty 0V: Not Drum Empty |
| 18 | Output | | 24V : Gun Solenoid ON for Application 1 0V: Gun Solenoid OFF for Application 1 |
| 19 | Output | | 24V : Gun Solenoid ON for Application 2 0V: Gun Solenoid OFF for Application 2 |
| 29 | Input | Analog 1 0 to 10 VDC | Line Speed Signal PUMP 1 (0-10 V) |
| 30 | Input | Analog 2 0 to 10 VDC | Line Speed Signal PUMP 1 (0-10 V) |



The connection between the main machine and FLEXDRUM can be done in two ways: with dry contacts or with voltage. If we select by voltage, the customer must connect his reference potential ($0V_{DC}$) to pin number 2.

Theses connections should be like this:

INPUTS (from main machine to FLEXDRUM)

| • | Pump enable: | | | |
|---|--|--|--|--|
| | - With dry contact: | link pin 1 and 4. | | |
| | - With voltage: | 24 V _{DC} to pin 4. | | |
| | | | | |
| • | Switch On/Off Equipment edge (OFF) | <i>:</i> positive edge (ON) ; negative | | |
| | With dry contact: | link pin 1 and 3. | | |
| | - With voltage: | 24 V _{DC} to pin 3. | | |
| • | External Standby: positive edge (ON); negative edg (OFF) | | | |
| | - With dry contact: | link pin 1 and 9. | | |
| | - With voltage: | 24 V _{DC} to pin 9. | | |
| | | | | |
| • | Line Speed Reference Pul | mp 1: 0-10V analogical signal | | |
| | - With voltage: | Pin 2 = 0V ; Pin 29 = 10V. | | |
| • | Line Speed Reference Pu | mp 2: 0-10V analogical signal | | |
| | - With voltage: | Pin 2 = 0V ; Pin 30= 10V. | | |
| • | Enable External Temperat | ture input 1: | | |
| | With dry contact: | link pin 1 and 11. | | |
| | - With voltage: | 24 V _{DC} to pin 11. | | |
| • | Enable External Temperat | ture input 2: | | |
| | With dry contact: | link pin 1 and 12. | | |
| | - With voltage: | 24 V _{DC} to pin 12. | | |
| ٠ | Enable External Temperat | ture input 3: | | |
| | - With dry contact: | link pin 1 and 13. | | |
| | - With voltage: | 24 V _{DC} to pin 13. | | |
| ٠ | Enable External Temperat | ture input 4: | | |
| | - With dry contact: | link pin 1 and 14. | | |
| | - With voltage: | 24 Vpc to pin 14. | | |

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OUTPUTS (from FLEXDRUM to main machine)

- Equipment Ready: normally open output
 - *Dry contact:* between pin 25 and 26. Contact Closed: equipment ready Contact Open: equipment not ready
 - Voltage: customer must give 24 V_{DC} to pin 25. In the pin 26 we will read:
 24 V_{DC}: equipment ready
 0 V_{DC}: equipment ready
- Equipment Fault: normally close output
 - *Dry contact:* between pin 25 and 28. Contact Closed: no fault in the system Contact Open: fault in the system
 - Voltage: customer must give 24 Vbc to pin 25. In the pin 28 we will read:
 24 Vbc: no fault in the system
 0 Vbc: fault in the system

• Drum Low Level:

- *Dry contact:* between pin 25 and 20. Contact Closed: Drum Low Level Contact Open: Not Drum Low Level
- Voltage: customer must give 24 V_{DC} to pin 25. In the pin 20 we will read:
 24 V_{DC}: Drum Low Level
 0 V_{DC}: Not Drum Low Level

• Drum Empty:

- *Dry contact:* between pin 25 and 21. Contact Closed: Drum Empty Contact Open: Not Drum Empty
- Voltage: customer must give 24 Vbc to pin 25. In the pin 21 we will read:
 24 Vbc: Drum Empty
 0 Vbc: Not Drum Empty

• Gun Solenoid for Application 1:

- Voltage: In the pin 2 we have 0V ; In the pin 18 we will read:
 24 V_{DC}: Solenoid ON
 0 V_{DC}: Solenoid OFF
- Gun Solenoid for Application 2:
 - Voltage: In the pin 2 we have 0V ; In the pin 19 we will read:
 24 V_{DC}: Solenoid ON
 0 V_{DC}: Solenoid OFF

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CHAPTER 4 MACHINE ADJUSTMENTS



The following adjustments should be made before the machine is switched on or while it is working. They will ensure that the machine works properly and safely.

This machine has a tactile screen where all the function parameters of each element of the machine are controlled.

FLEXDRUM is equipped with proportional temperature control for the resistances connected to double hose-gun channels and a special channel for heating the tank, with menus on screen to access parameter programming and control of the alternate current motor controlled by a vector frequency drive, operating clearance for the main machine, alarms and different operating functions (SEQUENTIAL START UP, ENERGY SAVING, etc.), which will be described later.

The speed of the pump can be adapted to the speed of the main machine, for this purpose this machine has an automatic programming function.

ENERGY SAVING function (Stand By) allows pre-selecting a % of the operating temperature in 3 groups. For these 3 groups different percentages of the operating temperature can be selected when the equipment is in ENERGY SAVING mode. Values between 40 and 100% can be selected.

SIMULTANEOUS START UP function: because the heat inertia of the equipment is much greater than for all the peripheral devices, these devices reach the programmed temperature much earlier than the equipment. This rapid heating process has an ageing effect on resistances and insulation. This phenomenon also creates excessive fluid pressure in the hoses.

To offset this problem, the equipment has been fitted with a preheat system that heats all the peripheral devices (hoses and guns) in a sequential manner, while the tank is heated at normal speed. When the tank reaches 75% of the programmed temperature, heat is supplied to the hoses. When the hoses reach 75% of the programmed temperature, heat is supplied to the guns.

The temperature programming allows pre-selecting the operating temperature for each device in a range between 0 and 240°C (32-464°F). Below 0°C (32°F) the device is permanently switched OFF.

The general parameters programming allows to enter operating parameters such as temperature measurement unit (°C or °F), clearance delay time, safety alarm temperature, temperature deviations that cause alarms, enabled options and functions such as time adjustment or sequential start up, etc.

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Time adjustment allows entering the current day of the week and the time on the timer. ON/OFF timer programming allows to enter automatic switch-on and switch-off times. Up to 2 on/off time groups can be programmed for each day of the week, and the switch-over to ON, OFF or ENERGY SAVING.

Whenever a device reached the programmed safety temperature, an alarm signal will be shown on the screen.

The equipment also includes a safety system with a bimetallic thermostat, adjusted to 240°C. When the thermostat is triggered, it will de-activate the main switch coil, disconnecting the power to the resistances but continuing to supply the control electronics, so that it can identify the device that is the source of the problem on the screen. After repairing the fault, the equipment has to be switched off and on again.

In the FLEXDRUM there are some optional elements, which are better to order when the equipment is built, like a proportional valve or solenoid, to control the adhesive recirculation to the tank; level sensors, etc. However, these element can be ordered later, but usually will be necessary to modify some mechanical parts of the equipment. These options have to be activated from the tactile screen.

Also, there are more optional element, but in this case you can order them when you want, because their installation it is very easy and fast. For it will not be necessary to modify any mechanical parts of the equipment, only "plug and play". These elements also have to be activated from the tactile screen. These are the next:

- SmartFlow: a compact box with four pressure transducer inputs, to control and monitoring the real pressure in the gun; and four flowmeter inputs, to control the real grammage applied.
- SmartHeat: a compact box with four hose gun temperature channels, to add an extra heating channels to the equipment. The temperature sensor of these boxes can be Ni120 or Pt100, independently of the equipment sensor.
- SmartDrive: a compact box with one or two frequency drives to add an extra pump control to the equipment. The maximum number of pumps between the equipment and the SmartDrive will be four.



4.2. CONTROL PANEL:

4.2.1. Buttons

The buttons most common are the next:

HOME BUTTON: this button is in the right below corner of the screen. Clicking on it, we will go to the main screen.



NAVIGATION BUTTONS: clicking on these buttons, we will move arround the pages which appear a list of elements, for example, temperature and alarm page.



BACK BUTTON: clicking on this button, we will go to the previous page.



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4.2.2. Main Page

When the equipment is switched on the main screen is opened automatically. Press the different areas on the screen to configure the equipment.

| り | | | × | OFF |
|---|-------|---------|------|---------|
| | 11111 | 0xxxxxD | (OPD | |
| 1 | 20 C | | 44 | 6 |
| 2 | | | | 0.0 rpm |
| 3 | | | | |
| 4 | - | | | |
| 5 | | | | |
| 6 | | | | |
| 7 | | | | |
| 8 | | | | / |

The appearance of the top part will be different if we have installed some sensor level or pro coat box

| じ | | | × | 0.0 mm | OFF |
|---|-------|---------|---|--------|-------|
| | 11111 | 0xxxxxD | | 10 | |
| 1 | 20 C | 1 | | | |
| 2 | | | | 0.0 |) rpm |
| 3 | | | | - | |
| 4 | | | | | |
| 5 | | | | | |
| 6 | | | | | |
| 7 | | | | | |
| 8 | | | | | |



The different areas and buttons of the screen are the next:



Temperature Zone:

In this area, we can see the real temperature of each channel. The background colour will change depending on the status of the channel:



Also, clicking on this area, we will go to the temperature settings page, when we can enable/disable the heating of the channels and change the temperature set point. We will see these settings in the point *4.2.3. Temperature Settings*.



Pumps Zone:

In this area, we can see the status of the pumps. There are three lines and an icon for each pump. The meaning is the next:

| ¹ O 0.0 rpm | <i>Pump icon</i>: it symbolizes the status of the pump. If its colour is black, the pump will be disabled. If its colour is green, the pump will be enabled. If its colour is green and the icon is turning, the pump will be moving. |
|-------------------------------|--|
| Ø | Speed (top line): it indicates the real speed of the pump. |
| 0.0 rpm | <i>Pressure (top line)</i> : it indicates the real pressure measured. If pressure transducer is not installed, a line will be appeared. |

Also, clicking on this area, we will go to the pump settings page, when we can enable/disable the pump moving, change the set point speed, etc. We will see these settings in the point *4.2.4. Pump Settings*.

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Buttons:





Clicking on this button, we will go to the alarms page. We can see it in the point *4.2.6. Alarms.* The colour of the button can change depending on the status of the system. The button will blink in the next colours:





System ON



CONFIGURATION button

Clicking on this button, we will go to the configuration page. We can see it in the point *4.2.5. Configuration.*



DRUM LEVEL button

Clicking on this button, we will go to the tank level page. We can see it in the point *4.2.7. Tank Level.* The appearance of this button will change depending on the level of the equipment and the sensors installed.



PROCOAT BOX button

Clicking on this button, we will go to the Procoat box page. We can see it in the point *4.2.8. Procoat Gun*. In the top part of this button, we will see a numeric value which corresponds with the actual width of the Procoat gun.

Status of the equipment:

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OFF

System OFF

In this situation, the main contactor of the equipment will be off, so the equipment will be without power. The temperature channels will not be heated, and the pumps will be stopped.



In this situation, the main contactor of the equipment will be on and the temperature channels enabled will be heated. If the heating mode is sequential, next to the icon will be appear a number with the zone which is

sequential, next to the icon will be appear a number with the zone which is being heated (1 - tank; 2 - Hoses; 3 - Guns and Aux). If the heating mode is simultaneous, no number will appear.



When all temperature set points have been reached, the system will wait a time indicated in the temperature operating parameters. After this time, the equipment will be ready to work. In the bottom part will appear the time left. You can change this time in configuration settings page.



When all temperature set points have been reached and the system has waited the waiting time, the system is ready to work. If the working parameters are correct, the pumps enabled will be moved.



System WARNING

If some situation has caused a warning in the system, the appearance will be like this. In this situation, the pumps will be moved if the working parameters are correct.



If some situation has caused a fault in the system, the appearance will be like this. In this situation, the pumps will not be moved.

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4.2.3. Temperature Settings

Path: Home Screen/Temperature Zone

Clicking on temperature zone in the main page, we will go to the next page. In this page, we can adjust the temperature set point of each channel and enable/disable the heating of the channels.

Only will be appear the temperature channels installed in the equipment, it will depend on the number of pumps and hose – gun outputs of the equipment.

The icons are the next:

\$\$\$\$\$\$

Tank: Plate of the drum.

Hose Channels:

From 1 to 8, depending on the outputs.

Gun Channels:

From 1 to 8, depending on the outputs.

In the top part, we have some buttons:

٨h

Temperature Set Point Page

Clicking on this button, we will go to the next page, when we can adjust the temperature set point of each channel.

Doing double click on the icon, the set point temperature of the line 1, will be pasted in all channels of the same column.

Doing double click on the "SET" text, the set point temperature of the top element in line 1 will be pasted in all channels.

| din . | 0 | | | тхт | (i) |
|-------|-------|----------|------|-----|------------|
| SET | hund | (100228) | dop | | |
| 1 | 20 °C | 0 °C | 0 °C | | |
| z | | 0 °C | 0 °C | | |
| 3 | | 0 °C | 0 °C | | |
| 4 | | 0 °C | 0 °C | | |
| 5 | | | | | |
| 6 | | | | | |
| 7 | | | | | |
| 8 | | | | | |

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Temperature Channel Enable/Disable Page

Clicking on this button, we will go to the next page, when we can enable or disable the heating of the temperature channels.

If the channel is enabled the background colour will be green, if not, it will be grey.



(i) Real Temperature Page

Keeping pressed this button, we will see the next page, where we can see the real temperature of all channels. If we release this button, we will return to the previous page.

If the text is "----", it means that the channel is not enabled and zero degrees are being measured.

If the text is "Error", it means there is not connected any element to the corresponding output or there is a short-circuit in this channel.

| (h) | (1) | | | тхт | i |
|-----|------|--------|-----|-----|---|
| | hand | GEREED | dop | | _ |
| 1 | 20 C | - | | | |
| 2 | | - | - | | |
| 3 | | | | | |
| 4 | | - | - | | |
| 5 | | | | | |
| б | | | | | |
| 7 | | | | | |
| 8 | | | | | |



TXT Temperature Text Page

Keeping pressed this button, we will see the next page, where we can see the texts of the temperature channels. If we release this button, we will return to the previous page.

We can change this text in the temperature configuration page. This text will also appear in the alarms.

| d) | U | | | тхт | (i) |
|----|------|---------|-------|-----|------------|
| | in | (Jacob) | dopo | | |
| 1 | DRUM | HOSE 1 | GUN 1 | | |
| 2 | | HOSE 2 | GUN 2 | | |
| 3 | | HOSE 3 | GUN 3 | | |
| 4 | | HOSE 4 | GUN 4 | | |
| 5 | | | | | |
| 5 | | | | | |
| 7 | | | | | |
| 8 | | | | | |

4.2.4. Pump Settings

Path: Home Screen/Pump Zone

Clicking on pump zone in the main page, we will go to the next page. In this page, we can adjust the working mode of the pump, start/stop movement of the pump, modify the set points of the different working modes, etc.

Only will be appear the pumps installed in the equipment.



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<u> Start / Stop Pump:</u>

With this button we can start/stop the movement of the pump.



are OK.

The small dot which appears in the right bottom corner, indicates if the pump has pump permission signal (received by digital input or by communications).



Pump Working Mode:

We can choose between the next working modes:

- **Manual:** enter in the set point box the desired speed value in rpm.
- Automatic: The unit receives an external analog signal (0-10V) signal, in proportion to line speed, which determines the likewise proportional pump speed. For example: 0 V = 0 rpm, 10 V = 100 rpm
- **Grammage:** in this mode, the system applies the desired weigh. It will be indicated in <u>gr/m2</u>. Previously it's necessary to set the working parameters.
 - ➔ If we have installed a flowmeter, we can do a close loop control to make sure that we are applying the desired weight.
- "GPP": Grams Per Product. In this mode, the system applies the desired weigh. It will be indicated in grams per product. Previously it's necessary to set the working parameters.
 - ➔ If we have installed a flowmeter, we can do a close loop control to make sure that we are applying the desired weight.

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- **Presure Control mode:** in this mode, the system will maintain the desired pressure indicated in the set point column, in <u>bars</u>.
 - ➔ It's necessary to have installed a pressure transducer. If not, we will not be able to use this control.



Pressing this button, we will go to the pump settings page, where we can adjust the advanced parameters of the pump working mode. Depending on the working mode select, the appearance of this page will change. We will explain this page later this page.

Set Point Value:

Set point value of the pump. The units of these parameters will change depending on the working mode selected.

Actual Values:

Actual values of the influencing variables in the pump working, like speed (rpm), and pressure (bars).

- Speed (left value): it indicates the real speed of the pump.
- **Pressure (right value)**: it indicates the real pressure measured. If pressure transducer is not installed, a line will be appear.

We can configure two transducer per pump, so the appearance changes in this page and in the main page too.

MAIN PAGE

PUMPS PAGE



0.0 rpm – 0.0 bar



4.2.4.1 Main Working Mode

<u>Manual:</u>

The pump will be moved at the speed indicated in the set point box.

| | | - | | | |
|------------|-----|------|-----|---------|---------|
| (1) Manual | · 🌣 | 10.0 | rpm | 0.0 rpm | 0.0 bar |

Pressing the settings button, we will go to the next screen:

| Pump 1 Pum | np Control |
|---------------------------------------|------------|
| Main Working Mode | Speed |
| Manual | 0.0 rpm |
| Additional Working Mode | Pressure |
| | |
| Ramp Compensat. | 0.0 bar |
| Ramp Compensat. Press Supervision | 0.0 bar |



Automatic:

The unit receives an external signal, in proportion to line speed, which determines the likewise proportional pump speed.



To convert this voltage signal in speed, we have to scale it. So, pressing the <u>set point button</u> we will go to the next screen.



Min.Ref: minimun reference.

It is the minimum value of the line speed voltage to considerer that the main machine is running. If the line speed is lower than this value, the system will consider that the main machine is stopped.

For example, in the previous picture, in the line speed value is lower than 0.1v Volts, the pump will not start.

Min.Speed: minimum speed.

If the pump is in condition to be moved, this value will be its minimum speed, even the pump speed scaled is less than this value.

For example, in the previous picture:

- While the line speed signal is from 0.1 to 0.5 Volts, the pump will be moved at 5 rpm
- If the line speed is higher than 0.5 Volts, the pump will follow the pump speed scaling curve.



Pressing the settings button, we will go to the next screen:

| Pump 1 Pur | np Control |
|-------------------------|------------------|
| Main Working Mode | Speed |
| Automatic | 0.0 rpm |
| Additional Working Mode | |
| Additional Working Wode | Pressure |
| Ramp Compensat. | Pressure 0.0 bar |
| Ramp Compensat. | 0.0 bar |



<u>Grammage:</u>

In this case, the system applies the desired weight, in gr/m2.

| Grammage - | ☆ | 10.0 gr/m2 | 0.0 rpm | 0.0 bar |
|------------|----------|------------|---------|---------|

To set the working parameters, pressing the set point button we will go to the next screen.

| Pump Control | | |
|--------------|--|--|
| | | |
| 10.0 | gr/m2 | |
| 1000.0 | mm | |
| 1.00 | g/cc | |
| 100.0 | % | |
| 0.0 | rpm | |
| | | |
| | 10.0 1000.0 1.00 100.0 0.0 | |

In the previous page we have to configurate the next parameters:

- Weigh set point: desired grammage for application, in gr/m².
- Application widht: in milimeters.
- Adhesive density: in grams/cc..
- *Fine Tunning*: aditional parameter to adjust the pump speed. If it is bigger than 100 %, the pump will turn faster than its theoretical speed. Otherwise, if this parameter is smaller than 100 %, the pump will turn slower than its theoretical speed.
- **Pump Min. Speed**: if the pump is in condition to be moved, this value will be its minimum speed.





If there is installed procoat gun, we can enable the button "Get Pro Coat". With this button, the application will be taken directly from procoat gun width.

| Pump 1 | Pump C | ontrol | |
|-------------------|--------|--------|--------------|
| Grammage Control | | | |
| Weight Set Point | 10.0 | gr/m2 | |
| Application Width | 10.0 | mm | Get Pro Coat |
| Adhesive Density | 1.00 | g/cc | |
| Fine Tuning | 100.0 | % | |
| Pump Min. Speed | 0.0 | rpm | |
| | | | |

Pressing the settings button, we will go to the next screen:



In this case, we have some buttons, which these are the next:





Pressing this button, we will go to the next page, where we will convert the line speed in meters per minute.



Min.Ref: minimum reference.

It is the minimum value of the line speed voltage to considerer that the main machine is running. If the line speed is lower than this value, the system will consider that the main machine is stopped.

For example, in the previous picture, in the line speed value is lower than 0.1v Volts, the pump will not start.



GPP: Grams per Product

In this mode, the system applies the desired weight, in grams per product.

| (1) GPP · ☆ 0.000 gr/p 0.0 rpm 0 |).0 bar |
|----------------------------------|---------|
|----------------------------------|---------|

To set the working parameters, pressing the set point button we will go to the next screen.

| Pump 1 | Pump Co | ntrol |
|------------------|---------|-------|
| Flow Parameters | | |
| Flow Set Point | 0.000 | gr/p |
| Adhesive Density | 1.00 | g/cc |
| Fine Tunning | 100.0 | % |
| Pump Min. Speed | 0.0 | rpm |
| | | |
| | | |

- Flow set point: desired grammage for application, in grams per product.
- Adhesive density: in grams/cc..
- **Pump Min. Speed**: if the pump is in condition to be moved, this value will be its minimum speed.

Pressing the settings button, we will go to the next screen:

| | \setminus | | |
|----|-----------------------|----------|------------|
| 1 | Pump 1 | Pump Con | trol |
| 12 | Main Working Mode | | Speed |
| | GPP | | 0.0 rpm |
| | Additional Working Mo | de | Pressure |
| | Ramp Compensat. | * | 0.0 bar |
| | Press Supervision | \$ | |
| | Press Boost | A JPIDI | Line Speed |

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Pressing this button, we will go to the next page, where we will convert the line speed in meters per minute.



- Min.Ref: minimum reference.

It is the minimum value of the line speed voltage to considerer that the main machine is running. If the line speed is lower than this value, the system will consider that the main machine is stopped.

For example, in the previous picture, in the line speed value is lower than 0.1v Volts, the pump will not start.



Pressure Control:

In this mode, the system will maintain the desired pressure indicated in the set point column, in bars.

| 1 Pressure | • 🌣 | 0.00 | bar | 0.0 rpm | 0.0 bar | |
|------------|-----|------|-----|---------|---------|--|
| | | | | | | |

Pressing the settings button, we will go to the next screen:

| Pump 1 | Pump Contro | bl |
|----------------------|-------------|------------|
| lain Working Mode | | Speed |
| Pressure | * • * | 0.0 rpm |
| dditional Working Mo | de | Pressure |
| Ramp Compensat. | \$ | 0.0 bar |
| Press Supervision | * | 1.0 |
| Press Boost | | Line Speed |
| | | 0.00 |

With this working mode, we only can enable "Ramp Compensation".

In this page we have some buttons, which are the next:



Alarms Settings Button:

Pressing this button, we will go to the next page, where we can adjust the warning and faults parameters of the control.

| Pump 1 | | Pum | np Contr | ol |
|-------------------------|-----------|------|----------|------|
| Pressure Control Parame | eters | | | |
| | Low (- Δ | SP) | High (+ | ∆SP) |
| Fault | 20.0 | bar | 20.0 | bar |
| Warning | 10.0 | bar | 10.0 | bar |
| | Start I | Jp | Worki | ng |
| Time Fault Delay | 20 | sec | 5 | sec |
| Min. Refer | rence | 0.00 |) V | |

- **Low Pressure Fault Limit**: set point decrement. If the real pressure is lower than this value, the system will go to fault mode.



- *High Pressure Fault Limit:* set point increment. If the real pressure is bigger than this value, the system will go to fault mode.
- **Low Pressure Warning Limit:** set point decrement. If the real pressure is lower than this value, the system will go to warning mode.
- *High Pressure Warning Limit:* set point increment. If the real pressure is bigger than this value, the system will go to warning mode.
- **Fault Time at Start Up:** during the line starting up, the system will wait the time specified here before to start to compare pressures to detect faults and warnings.
- Fault Time at Working: during the operating of the equipment, the pressure can suffer sudden changes but this duration is very short. So before reporting high or low pressure faults it is necessary that the pressure value is out of range for a longer time that the specified here.
- Min.Reference: it is the minimum value of the line speed voltage to considerer that the main machine is running. If the line speed is lower than this value, the system will consider that the main machine is stopped



Pressing this button we will go to the next page, where we can adjust the parameters of the PID controller.

| ACT | 0.00 bar | Kp | 1.00 | 1 |
|-----|----------|----|------|--------------------|
| - | | | | Save As Default |
| SP | 0.00 bar | Tn | 3.00 | Reset |
| TUC | 0.00 | Tv | 0.00 | Defaults |

In this page we will configure the PID controller parameters. These parameters are Kp (proportional gain), Tn (integral action time) and Tv (derivative action time).



If we push the "*Reset*" button, *Kp, Tn, Tv* and *DB* parameters will take the default values, which are the same that we can see in the picture above.

If we push the "*Save as Defaults*" button, the values which are in these parameters will be saved as default values.



Real Time Graph Button:

Pressing this button we will go to the next page, where we can view the actual and set point pressure values in real time. The graphic maximum and minimum value is adjustable. In this picture the low value is 0 bars, and the high value is 10 bar.



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4.2.4.2 Additional Pump Working Mode

In the bottom left part in the pump settings page, we have additional settings about pump working mode. These are "*Ramp Compensation*", "*Pressure Supervision*" and "*Pressure Boost*". But these additional modes are not compatible with all working modes of the pump.

Pressure Supervision:

In this mode only we can monitor the real pressure, so it works like a security system. If the pressure is not between the limit values previously configured, the equipment will detect faults or warnings



If we want to enable this mode, we have to press the "*Press Supervision*" button. If the background colour of this button is green, it means that this mode is activated. If it is grey, this mode will be disabled. Obviously, for this mode the system needs a pressure transducer.



Alarms Settings Button

To adjust the warning and faults parameters, we press this button, which will take us to the next page:



In this page we will configure the next parameters:

- **Low Pressure Fault Limit**: if the real pressure is lower than this value, the system will go to fault mode.
- *High Pressure Fault Limit:* if the real pressure is bigger than this value, the system will go to fault mode.



- *Low Pressure Warning Limit:* if the real pressure is lower than this value, the system will go to warning mode.
- *High Pressure Warning Limit:* if the real pressure is bigger than this value, the system will go to warning mode.
- **Fault Time at Start Up:** during the line starting up, the system will wait the time specified here before to start to compare pressures to detect faults and warnings.
- **Fault Time at Working:** during the operating of the equipment, the pressure can suffer sudden changes but this duration is very short. So before reporting high or low pressure faults it is necessary that the pressure value is out of range for a longer time that the specified here.



-

In "Pressure Boost Option", "Pressure Supervision" always is active, and it cannot be disactivated.



We use this mode to adjust the pump speed to get a better application in zones of ramp up and ramp down of the main machine.



If we want to enable this mode, we have to press the "*Ramp Compensation*" button. If the background colour of this button is green, it means that this mode is activated. If it is grey, this mode will be disabled.

It is not necessary pressure transducer or flowmeter, this control only affects to pump speed.



Ramp Compensation Settings Button

To adjust the parameters of the ramp, we press this button, which will take us to the next page:



The parameters are the next:

1. **Precompression time:** at the moment which the equipment receives the pump permission, the pump will be moved at 75 rpm for the time indicated in this parameter. We use this function to pressurize the system before the start up, very useful when the pump capacity is small.



- 2. Precompression time: at the moment which the equipment detects that main machine is accelerating, the pump will be moved at 75 rpm for the time indicated in this parameter. We use this function to pressurize the system during the first zone of start up.
- **3.** Compensation for acceleration: the theoretical pump speed will be increased this percentage during the acceleration zone. At the begining of acceleration, the compensation will be the parameter indicated here, but this value will be decreasing, and when the "Time for compensation for acceleration" is elapsed, there is no compensation and the pump speed will be theoretical speed.
- **4.** Time for compensation for acceleration: the compensation for acceleration will be done during this time. After this time, the pump speed will not be compensed.
- **5.** Compensation for deceleration: the theoretical pump speed will be decreased this percentage during the deceleration zone.
- **6.** Actual Compensation: in this box we can see the real compensation applied.
- 7. Actual line speed reference: in this box we can see the line speed signal.
- 8. Actual acceleration: in this box we can see the variation of the line speed in the time. This is very useful to adjust the acceleration and deceleration limits.
- **9. Deceleration limit:** limit for distinguish if the machine is decelerating or not. This value will be negative always.

If Actual acceleration <= Deceleration Limit \rightarrow Deceleration

If Actual acceleration > Deceleration Limit → Constant velocity

10. Acceleration limit: limit for distinguish if the machine is accelerating or not.

If Actual acceleration >= Acceleration Limit → Acceleration

If Actual acceleration < Acceleration Limit → Constant velocity



Pressure Boost:

This feature is used to ensure a correct application at the beginning of the cycle.



If we want to enable this mode, we have to press the "**Press Boost**" button. If the background colour of this button is green, it means that this mode is activated. If it is grey, this mode will be disabled. It's necessary to have installed a pressure transducer at the application point.

For this mode the system needs a pressure transducer.

In normal mode (without Pressure Boost) the pump needs some time to pressurize the system, and the result is a delay in the hotmelt application. With this "Pressure Boost" the system stabilizes the adhesive flow as soon as possible. It only will work when the main machine is accelerating or decelerating.



"Pressure Boost Option" in only available for "Grammage", "GPP" and "Automatic" modes.



To adjust the parameters of the mode, we press this button, which will take us to the next page:

| | Actual | Line Stopped | Line Running |
|-----------------|----------|-----------------|-----------------|
| Pressure | 0.00 bar | 0.0 bar | |
| | Actual | Limt | |
| Acceleration | 0.00 V/s | 1.00 V/s | |
| Max. Working Ti | me | 30.00 sec | |

Here we can configure the next parameters:

- Pressure
 - *Actual:* here we can see the actual pressure

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- *Line Stopped:* if the main machine is stopped but the pump has permission signal, the pump will run to get the pressure indicated in this parameter.
- Line Running: if the main machine is running, the system will get the pressure indicated in this part. If we press the "Scaled" button, we will go to the next screen. The pressure set point will be variable, depending on the line speed reference.



- Acceleration
 - *Actual:* here we can see the actual acceleration of the main machine.
 - *Limit:* acceleration value from which we can consider that the machine is accelerating.

If Acc Act >= Acc Limit \rightarrow Acceleration

If Acc Act < Acc Limit \rightarrow Constant velocity



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To set this value it is required two steps:

1.- High limit: you must start the production and check the value of Acc ACT during acceleration phase. In case the value oscillates between 0 and other value (35 for example). The value of Acc Limit must be lower than this value.

2.- Low limit: during normal production, small variation in speed could appear, in this case the value of Acc ACT could change. You must check these little changes and fix the value of Acc Limit upper these values.

- **Max. Working Time**: if the pressure boost control cannot adjust the real pressure to the set point pressure in a time lower than indicated in this parameter, the system will notify fault.



Pressing this button we will go to the next page, where we can adjust the parameters of the PID controller.

| ACT | 0.00 bar | Кр | 2.00 | - |
|-----|----------|----|------|----------|
| | | | | Default |
| SP | 0.00 bar | In | 1.00 | Reset |
| OUT | 0.00 | Tv | 0.00 | Defaults |

In this page we will configure the PID controller parameters. These parameters are Kp (proportional gain), Tn (integral action time) and Tv (derivative action time).

If we push the "*Reset*" button, *Kp*, *Tn* and *Tv* parameters will take the default values, which are the same that we can see in the picture above.

If we push the "*Save as Defaults*" button, the values which are in these parameters will be saved as default values.

We have an additional parameter, which is the *Operating Range*. If the current pressure is out of this set point range, the pressure boost will

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work until the pressure is inside the range. In this moment the pressure boost will not work.



Pressing this button we will go to the next page, where we can view the actual and set point pressure values in real time. The graphic maximum and minimum value is adjustable. In this picture the low value is 0 bars, and the high value is 10 bar.



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PRESSURE BOOST WORKING MODE:

The working mode is the next:

CASE 0:

- Main machine stopped (Line Speed signal = 0)
- Pump permission signal disabled
- Pump stopped

- <u>CASE 1</u>:

- **Main machine stopped** (Line Speed signal = 0)
- Pump permission signal enabled
- Pump will run to get the pressure indicated in "Line Stopped Pressure".

- <u>CASE 2</u>:

- o Main machine running and accelerating
 - Line Speed signal > 0
 - Acceleration Actual > Acceleration limit
- Pump permission signal enabled
- Pump will run to get the pressure indicated in "Line Running Pressure".

CASE 3:

- Main machine running and at constant speed
 - Line Speed signal > 0
 - Acceleration Actual < Acceleration limit
- Pump permission signal enabled
- Pump will run to get the pressure indicated in "Line Running Pressure". When the pressure in inside the "operating range" indicated in PID page, the pump will stop to control pressure, and the RPM will get the theoretical value, depending on the working mode selected (Grammage Control, GPP or Automatic).



CASE 4:

_

- Main machine running and decelerating
 - Line Speed signal > 0
 - Acceleration Actual > Acceleration limit
- Pump permission signal enabled
- Pump will run to get the pressure indicated in "Line Running Pressure".



4.2.4.3 Pneumatic Regulation Settings

To set the working parameters of the pressure regulator wil will press the next button .



Depending on the pressure regulator selected in "*Equipment Accessories*" page, the appearance of this page will change. In this picture, in the pump one we are using a proportional valve, and in the pump two the pressure regulator is controller by and solenoid.

PROPORTIONAL VALVE

We can distinguish three working types:

- **Manual**: the working pressure will be fixed and equal to the value indicated in the grey box. This pressure must be between 0 and 6 bar. The white box indicates the actual pressure of the proportional valve.



Automatic: the working value will be variable in function of the line speed. If we push the "Scale" button we will go to the scaled page. The pressure must be between 0 and 6 bar.

| 1 | Automatic | • | Scaled | 0.0 | bar | Gun Signal |
|---|-----------|---|--------|-----|-----|------------|
|---|-----------|---|--------|-----|-----|------------|

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Uniflow: in this working mode we will have two working pressures, one with gun open and other with gun closed. The pressure can be fixed or variable (depending on the rpm or depending on the application width). The different working modes are explained below:

> o Fixed: in settings the working pressure will be fixed and equal to the value indicated in the grey boxes. These pressures must be between 0 and 6 bar. The white box indicates the actual pressure of the proportional valve and the gun signal colour indicates if it is open (green) or closed (red).

| Pump 1 Pro | portional Va | lve | |
|----------------------------|--------------|-----|---|
| Iniflow Fix Set Point | | | _ |
| Gun Applying Pressure: | 6.0 bar | | |
| Gun Not Applying Pressure: | 3.0 bar | | |

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 \circ *Variable:* the working values will be variable in function of the rpm or application width. If we push the Settings button we will go to the scaled pages. The pressures must be between 0 and 6 bar.

• Depending on rpm:





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- Depending on application width:









4.2.5. Configuration

Path: Home Screen/Configuration Button

It is possible to access to these pages clicking on the settings button in the main page.





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4.5.2.1. User level

| Ser Name: User Level: | admin highLevel | Login | Logout |
|--------------------------|--------------------|-------|--------|
| Add User | Delete User | | |
| Edit User | Change Password | | |

| Level | Functions |
|------------|---|
| | Switch on/off equipment |
| | Enter/exit standby |
| | Adjust terminal settings |
| Operator | Start/stop pumps |
| | Adjust pump working settings (optional) [*] |
| | Enable Temperature Channels (optional) [*] |
| | Change Temperature Set Point (optional) [*] |
| Supervisor | All "Operator" functions |
| | [*] Allow operator change optional settings |
| | All "Supervisor" functions |
| Programmer | Access most system setup parameters |
| | Configure the "System Designer" |
| highLevel | Be able to create users |
| | Only for Melton Technical Service |

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4.2.5.2. Terminal settings

| anguage | Real time clock setting |
|------------|----------------------------|
| | DT#2022-08-03-12:04:45 |
| Brightness | Software Version |
| | PLC : X065PLEX01 V22.07.27 |
| | HMI: X065SCEX01 V22 07 27 |

| ⋫ |
|---|
|---|

Real time clock settings

| Ter | rminal S Real time c | ettings lock settin | g | | | | |
|-----|-------------------------|------------------------|-------|--------|------|---|----|
| | 3 | 8 | 2022 | [| 12 | 6 | 0 |
| | 3 | 8 | 2022 | | 12 | 6 | 17 |
| ◀ |] | | Apply | y Char | nges | | |



4.2.5.3. Connect / Disconnect Timing

On this screen the user can program a number of hours for each day of the week, so when the real time is the same that programmed in this page, the machine is turned on, turned off or change to standby mode automatically.

| | | Ena | bled | | DT#2022-08-03-12:08:12 |
|------------|----|-----|------|----------|------------------------|
| Hour ON 1 | 10 | : | 30 | Standard | Monday Tuesday |
| Hour OFF 1 | 11 | : | 45 | OFF | Wednesday |
| | | | | | Thursday |
| Hour ON 2 | 0 | 1. | 0 | Stand By | Saturday |
| Hour OFF 2 | 0 | : | 0 | Stand By | Sunday |

The possible options are the next:

- *Turn on the equipment*: set the desired time, and in the right button put "*Standard*".
- *Turn off the equipment*: set the desired time, and in the right button put "*OFF*".
- Change to Standby Heating Mode: set the desired time, and in the right button put "Standby".
- Change to Normal Heating Mode: set the desired time, and in the right button put "Standard".

To activate this mode, we have to push the "**Disabled**" / "**Enabled**" button. If this mode is activated, text "*Enabled*" must be in the previous button and near to the clock will appear a clock like this \mathfrak{D} .

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4.2.5.4. Temperature Configuration

| War | ning / Faults Pa | rameters |
|-----|------------------|-----------|
| c | Operating Paran | neters |
| | PID Paramet | ers |
| Ext | ernal Temperatu | ire Input |

Warning / Faults Parameters

In this page we adjust the set point increments to generate alarms: warnings and faults. Also we define the lower and higher limits for temperature. If the actual temperature is higher than temperature high value, automatically the equipment will turn off.

| | Low Temperature (- ∆SP) | High Temperature (+ ΔSP) | Temperature High Value |
|---------|----------------------------|------------------------------------|------------------------------------|
| Fault | 20 °C | 20 °C | 240 °C |
| Warning | 10 °C | 10 °C | |
| | Low Fault Delay | Temperature Set Point Low Value | Temperature Set Point High Valu |
| | 10 sec | 0 °C | 240 °C |

Operating Parameters

In this page we adjust the parameters about the operating of the equipment.

| Т | emperature C | onfigurat | tion |
|----------------------|--------------|-----------|------|
| Operating Parameters | | - | |
| Heating Mode | Simultar | eous | |
| Temperature Units | °C | | |
| Waiting Time | 15 min | | |
| Auto-Stanby Time | 0 min | | |
| Standby Values | 70 % | 70 % | 70 % |
| 21 | | GIIIID | 400 |

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- *Heating mode*: sequential (progressive heating of the three zones) or simultaneous (heating of the three zones at the same time.
- **Temperature Units**: selection between °C / °F for programming and visualization.
- *Waiting Time*: the user can choose the time it takes the machine to give permission to the pump when everything is OK.
- **Auto-Standy Time:** if the equipment is ready to work, but for the time indicated in this box any pump does not have permission, the equipment will go to standby mode automatically. When we receive the pump permission, the equipment will return to normal heating mode, and when it is ready again, the pump will be moved if the working parameters are OK.
 - → If we do not want to use it, we only have to put **ZERO** in this box, and this function will be disabled.
- **Stand by Values**: values in %, to reduce the set point temperature in each zone: zone 1 (tank and manifolds); zone 2 (hoses); zone 3 (guns and auxiliary).

PID Parameters

These parameters are set in the factory. If there is any problem please contact to the Valco Melton Technical Service.

We use the arrows up and down to select the desired temperature element.

- **Reset All Channels**: we have to make double click on this button, and all temperature channels will take the default values.
- **Reset Current Channel**: we have to make single click on this button, and the temperature channel selected in this moment will take the default values.
- **Save Current Channel**: we have to make single click on this button, and the temperature parameters in the channel will save as default values.
- **Save All Channels**: we have to make single click on this button, and the temperature parameters in all channels will save as default values.





External Temperature Inputs

With this type of control, you can enable or disable the heating of temperature channels using external digital inputs. We have available four digital input, and we can use these like we want. See the electrical diagrams to know which are these inputs.

| able Extarnal Channel Disabling No mp. Low Fault Time 0 mi Channel Assignment Channel Assignment O M Image: Configuration Image: Configuration <td co<="" th=""><th></th><th></th><th></th><th></th><th></th><th></th><th>2</th><th></th><th>~</th></td> | <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th>2</th> <th></th> <th>~</th> | | | | | | | 2 | | ~ |
|--|---|--------------|----------------|---------------------------|----------------------------------|----------------------------------|--|-------------|--------------------|---|
| np. Low Fault Time 0 mi Channel Assignment Temperature Configuration nal Temperature Inputs 0 ~ No 1 0 Л 0 Л 0 Л 2 0 Л 0 Л 3 0 Л 0 Л 4 0 Л 0 Л 5 | nable E | xtarnal | Channe | el Disa | abling | | | No | 6 | |
| Channel Assignment Temperature Configuration nal Temperature Inputs 0~N 1 0 Л 0 П 0 Л 2 0 Л 0 Л 3 0 П 0 Л 4 0 Л 0 Л 5 | emp. Lo | w Faul | t Time | | | | | 0 | min | |
| Temperature Configuration o~N/ and Temperature Inputs cempo dOp > 1 0 | | | | | С | hanne | el Assigi | nment | t | |
| Остор Солоно Солоно< | | | | | | | | | | |
| 1 0 Л 0 Л 0 Л 2 0 Л 0 Л 3 0 Л 0 Л 4 0 Л 0 Л 5 | ernal Ter | nperatu | T ire Input | 'emp | perati | ure C | Config | gura | tion 0-Not | |
| 2 0 Л 0 Л 3 0 Л 0 Л 4 0 Л 0 Л 5 | rnal Ter | nperatu | T Ire Input | emp s | berati ≖0 | ure C बद्ध | Config | gura | tion ₀-Not ≥ | |
| 3 0 <u><u><u></u></u> 0 <u><u><u></u></u> 4 0 <u><u><u></u></u> 0 <u><u><u></u></u> 5</u></u></u></u> | ornal Ter 1 | mperatu | T ure Input | emp s c= | peratu ≖⊃ Γ | ure C | Config ⊉ Л | gura | tion ₀-Not ≥ | |
| 4 0 <u>N</u> 0 <u>N</u> 5 | rnal Ter 1 2 | nperatu 0 | T ure Input | emp s o o | Deratu ■D 「 」 「 」 | ure C eदि o | Donfig Do L L | gura /// | tion ⁰∽Not ≫ | |
| 5 | ernal Ter 1 2 3 | nperatu | T Ire Input | emp s o o o | Deratu ■D 「 」 「 」 | 42 0 0 | Donfig | gura | tion º∽Not ≫ | |
| | rmal Ter 1 2 3. 4 | nperatu 0 | T ure Input | 'emp o 0 0 | Deratu π π π | ure C =CC 0 0 0 0 | Config D A A A A A | gura | tion ₀∽Not ≥ | |
| 6 | rmal Ter 1 2 3 4 5 | nperatu 0 | T ire Input | emp s 0 0 0 | Deratu D R R R R | ure C 0 0 0 | D D D D D D D D D D D D D D | gura | tion ⁰∽Not ≥ | |
| 7 | rmal Ter 1 2 3 4 5 6 | nperatu 0 | T Ire Input | "emp o 0 0 | Deratu π π π π | ure C ={3 0 0 0 0 | Donfig D A A A A A | gura /// | tion ₀∽Not ≫ | |
| 8 | nal Ter 1 2 3 4 5 6 | nperatu 0 | T ure Input | emp ces 0 0 0 | n R R | ure C درت 0 0 0 | Config ₽ Л Л Л Л | gura | tior ₀~№ | |

So, if we want to work with the external temperature control, first we have to enable it in the touch screen, putting YES in the button "*Enable External Channel Disabling*".

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Temperature Low Fault Time: if the system is ready and we start to heat one channel using these external inputs, the system will wait this time before showing low temperature faults and alarms. In this way, the system will continue working without any fault.

After that, we will go to the "*Channel Assignment*" page (right picture), where we will establish the relationship between temperature channels and digital inputs.

- Numbers from 0 to 4:
 - 0 → Not in use. The channel with the number 0 will not be enabled or disabled by any digital input.
 - 1,2,3,4 → digital input for enabling or disabling temperature channel.
- Button Normally Open / Normally Close
 - In Normally Open → if input active, the channel will NOT BE HEATED.
 - **Wormally Close** \rightarrow if input active, the channel will BE HEATED.

After the assignment, we have to enable in the touch screen all channels which will be heated. If one channel is not enabled in the touch screen, it never will be enabled or disabled with these inputs.

For example, we suppose that we use the digital input number 1 for heating the Drum and the Hose 1. With the Drum we use the normally open option, and with Hose 1 we use the normally close.

So, in the moment when the digital input 1 is active, the Drum will be heated and the Hose 1 will not be heated.

We can see it in the next picture.

Channel Assignament Page



Temperature Enable





So, the colour code in these cases is the next:

Channel disabled OFF
Channel enabled and heating ON
Channel enabled and not heating ON

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4.2.5.5. Pump Configuration

In this page we configure all about the pump phsycal settings.

| | Pump Enable | Pump Type | Pump cc/rev | Transducer Enable | Motor Settings |
|---|----------------|--------------|----------------|----------------------|-------------------|
| 1 | YES | Ð | 30.00 | r | -0 |
| 2 | NO | -0 | 0.00 | r | -0 |

Pump Enable: we select if this pump is installed or not.

<u>Pump cc/rev:</u> capacity of the pump. If it is dual, we will introduce the capacity of one string.

<u>**Transducer Enable:**</u> we will assign transducers to the pumps. We can add two transducers per pump. To enable the transducer, press "**Yes**/**No**" button.

<u>Motor Settings:</u> In this page we will assign all the parameters of the motor

| Pump 1 M | otor Type: 1.5 k | w - |
|--|---|-----|
| Nominal Speed (rpm) | 3450 | 4 |
| Nominal Frecuency (Hz) | 120 | |
| Nominal Voltage (V) | 360 | |
| Cos Phi | 0.80 | |
| Pump Ratio (i) | 27.415 | |
| | | |
| Nominal Current (A) | 3.9 | |
| Nominal Current (A) umps Configuration Pump 1 M | 3.9 otor Type: 1.5 k | w - |
| Nominal Current (A) Umps Configuration Pump 1 M Slip Compensation (%) *speed -> +sli | 3.9 otor Type: 1.5 k | w - |
| Nominal Current (A) Umps Configuration Pump 1 M Slip Compensation (%) *speed -> + slip Current Limit (A) | 3.9 otor Type: 1.5 k 100.0 4.5 | w - |
| Nominal Current (A) UMPS Configuration Pump 1 M Slip Compensation (%) + speed -> + slip Current Limit (A) Thermal Current Limit (A) | 3.9 otor Type: 1.5 k 100.0 4.5 4.5 | w - |
| Nominal Current (A) UMPS Configuration Pump 1 M Slip Compensation (%) + speed -> + sli Current Limit (A) Thermal Current Limit (A) Acceleration Time (s) | 3.9 otor Type: 1.5 k 100.0 4.5 4.5 3.0 | w - |

Adhesive Density gr/cc: adhesive density.

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4.2.5.6. System Designer

Path: Home Screen/Configuration/Configuration Page 2/System Designer Button.

This page helps us to configure the machine depending on the numbers of pumps and outputs.

| System Designer | |
|----------------------|---|
| quipment Settings | |
| Pumps number | 1 |
| Hose - Gun Outputs | 4 |
| Coating Head Outputs | 0 |

4.2.5.7. Communications

In this page we adjust all parameters about the communications.

| ENABLE | No |
|--------|----|
| | |
| | |
| | |
| | |
| | |

With the button "No/Yes" we can disable/enable the comunications. We can select between: OPCUA or MODBUS TCP.

| INABLE | Yes |
|---------------|---------------------|
| Protocol: | OPC UA |
| Control Mode: | Dual(HMI + Comm.) - |
| | |
| | |
| | |

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| ENABLE | Yes |
|---------------|---------------------|
| Protocol: | MODBUS TCP |
| Control Mode: | Dual(HMI + Comm.) - |
| | |
| | |

IMPORTANT NOTE:

For all about items about communication process, please see Annex D.

- Control Mode:
 - **Standard (HMI + I/O):** in this case, the control of the machine will be done with the HMI and main machine interface connector, so the communication will not affect to the machine working mode. Only could be used for reading the variables of the equipment, but the working parameters of the equipment will not be modified by the communications.
 - **Communications:** in this case, the control of the machine will be done only by communications. The working parameters in the touch screen will be locked, and you can not modify any parameter.
 - **Dual (HMI + Comm.):** in this case, the control of the machine will be done in two ways, by communications and by the touch screen.



4.2.5.8. Equipment Accessories

In this page we add all accessories which has the equipment. We can distinguish two types:

| Equipment Acc | esories | |
|-----------------|---------|-----------------------|
| Procoat Control | | Pneumatics |
| Installed | Yes | Pump 1 |
| | | Proportional Valve No |
| | | Keep pressure with No |
| | | Pump 2 |
| | | Proportional Valve No |
| | | Keep pressure with No |

- **Procoat Control:** if we have installed Procoat gun, in the main page appear a button with a gun. Pressing this button, we will go to a page where we can configure the settings about Procoat gun.
- **Pneumatic Regulator:** with this element we can control the return of adhesive to the tank. We can choose between:
 - PROPORT.VALVE:

'**NO'** if mechanical regulator is installed.

'YES' if the pneumatic regulator is controlled by a proportional valve.

KEEP PRESSURE:

'NO' if the pump is stopped the pressure will be released (the proportional valve pressure goes to zero).

'**YES**' with the pump stopped, the pressure is kept (depending on the working value).

The control parameters of these elements will be adjusted in the pumps page, where will appear a button in the top part of the page.



4.2.5.9. Options

| First Start Up | Main Switch |
|--|-------------|
| llowing operator to change temperature | Yes |
| Allowing operator to control pumps | Yes |
| ine Speed Mode | Common |

- First Start Up: we can select between "*Main Switch*" (the equipment will be switched on al the same time that the main switch) or "*Display*" (the equipment will be switched on when the button *ON/OFF* in the main page is pressed.
- Alowing operator to change temperature: we can choose if the operator can modify the temperature parameters or not. If we set "*NO*", the operator will not be able to change the temperature set point or enable/disable any channel.
- Alowing operator to control pumps: we can choose if the operator can modify the pumps parameters or not. If we set "*NO*", the operator will not be able to change the pump working mode or adjust its working parameters.
- Line Speed Mode: if we have 2 pumps we can choose if the line speed is independent for each pump or the line speed is common for both pumps.



4.2.5.10. Tandem Mode Configuration

In this page we adjust all parameters about the Tandem Mode Configuration.

| Tandem Mode Configuration | |
|---------------------------|----|
| ENABLE | No |
| | |
| | |
| | |
| | |
| | |

With the button 'No/Yes' we can disable/enable the Tandem mode.

In this part you can see the status of the Tandem communication process.

Tandem communication OK

Pressing the button you restart the Tandem communication process, if it is in fault mode.

Next, a step-by-step example of a configuration of two flexdrums working in Tandem mode is shown.

When we work in Tandem mode we will have two *Flexdrums*, one we will configure as a slave and the other as a master.



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 http://www.meltonhotmelt.com



First of all, we must check that the IP of the two plates is in range, and they are not the same.

First, press and hold the screen over an area where there is no button e.g.

| С | onfiguration - Pa | ag. 1 | | DT#2024-04 | 4-07-15:02:04 |
|------------|----------------------|--------------|-------------|------------|---------------|
| | - | Terminal Se | ettings | | |
| | Conne | ect / Discor | nnect Timer | | |
| | Temp | erature Co | nfiguration | | |
| | Ρι | imps Confi | guration | | |
| | { | System De | signer | | ¥ |
| . (| Jser Level: admin | Login | Logout | | |

When the following tab appears, click on Show system settings

| Configuration | - Pag. 1 | | DT#2024-04-10-10:29:04 |
|----------------------|----------------|--------------|--|
| | Terminal S | ettings | * |
| C | onnect / Disco | nnect Timer | |
| - | emperature Co | onfiguration | Pan mode |
| - | Pumps Confi | iguration | Settings Project Manager Update Logging |
| | System De | signer | Show Log at Boot |
| | o yolom be | Signor | Show system settings |
| | | | About 🕨 |
| User Level: admin | Login | Logout | A |

We will open the system settings. Here press on Network

| System Settings |
|-----------------|
| Language |
| System |
| Logs |
| Date & Time |
| Network |
| Services |
| Management |
| Displ ay |

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Next, press on EDIT and then on Network Interfaces

| HMI-ae82 HMI-ae82.local | | | |
|----------------------------|----------------------------|----------------------------|----------------------------|
| | | | |
| | | | |
| | | | |
| | HMI-ae82 HMI-ae82.local | HMI-ae82 HMI-ae82.local | HMI-ae82 HMI-ae82.local |

Here you can edit the IP address and subnet mask of the screen.

| Avahi Hostname | HMI-ae82.local | |
|--------------------|-------------------|--|
| Network Interfaces | | |
| Name | e th0 | |
| Label | WAN | |
| MAC | 00:30:d8:0b:ae:82 | |
| DHCP | \bigcirc | |
| Address | 10.24.91.135 | |
| Netmask | 255.255.255.0 | |

For example, we can set the next address:

• Master

| Address | 10.24.91.135 |
|---------|---------------|
| Netmask | 255.255.255.0 |
| Slave | |

| Address | 10. 24. 91. 136 |
|---------|-----------------|
| Netmask | 255.255.255.0 |



Going back to the Tandem Mode configuration page, we must indicate in the configuration of each Flexdrum what its fuction, if it is the master or the slave.

| Tandem Mode Config | uration | |
|--------------------|----------------|-----------------|
| | | Yes |
| Working Mode: | Master - Slave | |
| Function: | Master | |
| Slave IP Address: | 10.24.91.136 | |
| Slave Port Number: | 501 | |
| Slave Status: | NO STATUS | |
| 1 | | Tandem Settings |

Flexdrum 1: Master

| Tandem Mode Configuration | | | | | |
|---------------------------|----------------|-----------------|--|--|--|
| | | Yes | | | |
| Working Mode: | Master - Slave | | | | |
| Function: | Slave | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | Tandem Settings | | | |

Flexdrum 2: Slave



Next, we will indicate the address of the slave on the Flexdrum master.

| Tand | Tandem Mode Configuration | | | | |
|------|---------------------------|----------------|-----------------|--|--|
| EN | | € | Yes | | |
| | Working Mode: | Master - Slave | | | |
| | Function: | Master | | | |
| | Slave IP Address: | 10.24.91.136 | | | |
| | Slave Port Number: | 501 | | | |
| | Slave Status: | NO STATUS | | | |
| | | | Tandem Settings | | |

Depending on the working mode selected, the appearance of this page will change.

Master-Slave Working Mode:

| Tai | Tandem Mode Configuration | | | | | |
|-----|---------------------------|----------------|-----------------|--|--|--|
| | | | Yes | | | |
| | Working Mode: | Master - Slave | | | | |
| | Function: | Master | | | | |
| | Slave IP Address: | 10.24.91.136 | | | | |
| | Slave Port Number: | 501 | | | | |
| | Slave Status: | NO STATUS | | | | |
| ◀ | | | Tandem Settings | | | |

Pressing the button '*Tandem Settings*', we will go to the next page, where we can disable the heating of the temperature channels when the flexdrum is in waiting mode.

If the channel is disabled, the background colour will be green, if not, it will be grey.



| | | | <u>ارک الا</u> | |
|------------|------|-----|----------------|--|
| . [| 0.55 | | | |
| ۱ <u> </u> | OFF | OFF | | |
| 2 | | OFF | OFF | |
| 3 | | OFF | OFF | |
| 4 | | OFF | OFF | |
| 5 | | | | |
| 6 | | | | |

We can select between two conditions to determine when the slave flexdrum should start working:

Slave start pump condition

Low Level

When the Flexdrum that is working reaches a low level, the Flexdrum that was switched off begins to work (the pump will start).

Slave start pump condition

When the Flexdrum that is working reaches an empty level, the Flexdrum that was switched of begins to work (the pump will start).

Empty Level

Synchronization Working Mode:

| Tandem Mode Configuration | | | | |
|---------------------------|-----------------|--|--|--|
| ENABLE | | | | |
| Working Mode: | Synchronization | | | |
| Function: | Master | | | |
| Slave IP Address: | 10.24.91.136 | | | |
| Slave Port Number: | 501 | | | |
| Slave Status: | NO STATUS | | | |
| Speed Relationship: | 0.0 % 100.0 % | | | |

The two flexdrums work simultaneously and we must indicate their Speed Relationship.

| | Master | Slave | |
|---------------------|--------|---------|--|
| Speed Relationship: | 0.0 % | 100.0 % | |

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Master – Slave

In this working mode, only one flexdrum pumps adhesive. One flexdrum will be working and the other waiting.

1. If both flexdrums are full, one works, and the other turns off the heating.



Flexdrum 1: Master

Flexdrum 2: Slave

2. When the flexdrum that is working reaches a low level, the flexdrum that was switched off begins to heat up.



Flexdrum 1: Master

Flexdrum 2: Slave

3. When the flexdrum that is working reaches empty level, it stops the pump, and begins to work the flexdrum that was waiting.

NOTE: the empty plate continues to heat until so that when we want to raise it and change the barrel, the flexdrum remains hot.





Flexdrum 1: Master

Flexdrum 2: Slave

4. When we replace the barrel of the empty flexdrum, and we lower the flexdrum again to put it inside the barrel, this flexdrum turns off the heating.



5. We return to point 1.



Synchronization

In this working mode the two Flexdrums work simultaneously, to achieve greater pumping rate.

For example, the master flexdrum will work 70%, and the slave 30%.

NOTE: these percentages are configurable on screen.

1. If both plates are full, one will function as a master (70%) and the other as a slave (30%).



2. When the flexdrum that is working as the master is empty, the pump will stop, and the flexdrum that was previously the slave will become the master and will work 100%.



Flexdrum 1: Master

Flexdrum 2: Slave

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3. When we replace the barrel of the empty Flexdrum, and we lower the flexdrum again to put it inside the barrel, this flexdrum begins to act as a slave, working at 30%.



4. We return to point 1.

Clicking on the tank level button in the main page, we will go to the next screen.

| Actual Drum | Comm. Drum |
|-----------------------|-----------------------|
| Up | Up |
| Drum In | Drum In |
| Low Level | Low Level |
| Down | Down |
| DRUM NO COMMUNICATION | DRUM NO COMMUNICATION |

In this page we can see the status of each flexdrum:

- DRUM NO COMMUNICATION
- HEAT OFF
- DRUM HEATING
- DRUM WAITING
- DRUM WORKING

In addition, we can make a request to change the plate by presing the following button:

Work with Actual Drum

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4.2.6. Alarms

ACTUAL ALARMS AND FAULTS

Whenever an alarm occurs, a banner will appear at the top or in the bottom of the screen, it depends on the page in which we are in that moment.

All current warning or fault events will be recorded in the alarm page. It is possible to access to this page following two different ways:

- Click on the alarm button in the main page
- Click on the alarm banner which appears in all pages.

| Т | ime | Description | | |
|--------------|---------------|---------------------------------------|---------|--|
| 08/04/2022 - | - 08:22:19 AM | FAULT Drive 1 CAN Communication Error | | |
| 08/04/2022 - | - 08:22:19 AM | FAULT I/O Module Comunication Error | | |
| 08/04/2022 - | - 08:45:10 AM | WARNING High Temperature Tank | | |
| | | | | |
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| | | | | |
| | | | | |
| | | | | |
| | | Reset | History | |
| | | | ristory | |

If the "*Reset*" button is pressed, the event will be acknowledged. However, the event will remain until the situation that caused it is not present. When this situation has disappeared, the event will not be shown.

If we push the "History" button, we will see the alarm history.



HISTORICAL ALARMS AND FAULTS

In this screen will be recorded every one of the events that have occurred during the system operation.

| From : | 08/04/22-08 | 42.42 | |
|-----------|------------------|--|----|
| To : | 08/04/22-08 | 47:42 | |
| | Time | Description | |
| 08/04/202 | 22 - 08:47:30 AM | FAULT Drive 1 CAN Communication Error | |
| 08/04/202 | 22 - 08:47:30 AM | FAULT I/O Module Comunication Error | |
| 08/04/202 | 22 - 08:47:30 AM | WARNING High Temperature Tank | |
| 08/04/202 | 22 - 08:47:31 AM | Power Board Communication Not Possible - Check wiring or the number of Outputs in "System Designed | r |
| 08/04/202 | 22 - 08:47:41 AM | Power Board Communication Not Possible - Check wiring or the number of Outputs in "System Designed | r" |
| | | | |
| | | | |
| | | | |
| (|) | [| |
| Bac | ckward | Forward | |
| | | | |

We can distinguish different events:

- *Fault events*: these will appear with a red background, for example, shortcircuit in temperature sensor.
- *Warning events*: these will appear with a yellow background, for example, high temperature warning.

All events that have been reset will appear with a white background, independently if it is a fault or a warning.



4.2.7. Tank Level

Clicking on the tank level button in the main page, we will go to the next screen.

In this page we can see the status of the level of the tank.

LOW LEVEL SENSOR

If we have installed a low level sensor, we will see the page like this.



This low sensor is simulated with the bottom left box inside the tank, which in this case is painted in green colour. It means that this sensor is detecting. However, if the colour of the sensor is blue, it means that this sensor is not detecting. If low level sensor does not detect, a warning will appear in the alarms screen.

If we have installed a security sensor, it will appear in the top left box inside the tank, which in this case is painted in blue colour. It means that this sensor is not detecting. If security level sensor detects, a warning will appear in the alarms screen.



☆

For additional settings, please the next button

| Drur | Drum Settings | | | | |
|---------------------------------|---------------|-------|--|--|--|
| Low Level Settings | | | | | |
| Empty Level Pump Running Volume | 0.0 L | 0.0 | | | |
| Air Invector Settings | | | | | |
| An injector bettings | | | | | |
| Barrels Consumed | 0 | Reset | | | |

Level Settings

If we press the settings button, we will go to the next screen. In it we can adjust the parameters about the empty level control and air inyector settings.

- Empty Level Pump Running Volume: In the set point we will indicate the volume (Liters) that the drum can work in vacuum (empty level sensor detecting).
 - → If we do not want to use it, we only have to put ZERO in this box, and this function will be disabled.
- Air inyector Settings: when the drum is moving up, an air inyector is activated. This air inyector is necessary to clean after a number of cycles, because if it is not clean at all, when the pail is moving up, the barrel can be compressed.
 - ➔ If the barrels consumed is higher than air inyector clean alarm value, the next alarm will be shown in HMI: "WARNING Clean Drum Air Inyector!"
 - So, if this alarm is shown, the first at all is to clean air inyector
 - After that, it is necessary to go to this page and press "Reset" button



4.2.8. ProCoat gun

| We | will add the | ProCoat for | om the | "Equipment | Accessories" | page. |
|----|--------------|-------------|--------|------------|--------------|-------|
| | | | | | | |

| Equipment Accesories | 5 |
|----------------------|---------------------------------|
| Procoat Control | Pneumatics |
| Installed Yes | Pump 1 |
| | Proportional Valve No |
| | Keep pressure with pump stopped |
| | Pump 2 |
| | Proportional Valve No |
| | Keep pressure with No |

Clicking on the gun button in the main page, we will go to the next screen.

In this page we can see the status of the ProCoat.

| Pro Co | at | | | | |
|--------|----------|----------|----------|-------|--|
| | | | | | |
| | 251.5 mm | 503.0 mm | 251.5 mm | \$ | |
| | 251.5 mm | 503.0 mm | 251.5 mm | CLOSE | |
| | | | • | | |
| | | < > | | | |
| | | | | | |



Menu to adjust Procoat Max/Min width and Offsets (Adjustments made at Valco Melton. Modify only if it is necessary).

| un Settings | | | |
|---------------|----------|----|---------------------------|
| Maximum Width | 1300.0 1 | nm | \$ |
| Minimum Width | 0.0 | nm | |
| Center Offset | 0.0 | mm | (+) : RIGHT (-) : LEFT |
| Spindle Pitch | 0.0 | mm | |

Homing of motors (Adjustments made at Valco Melton. Modify only if the motors do not close the gun completely).

In the previous page, if we press the next button () we can assign the application width which corresponds with each pump.

| A POINT | | |
|------------------|--------------|----|
| n Width Settings | | |
| Number of p | umps to use: | 1 |
| | | |
| Max Width | 1300.0 | mm |
| Max Width | 1300.0 | mm |
| Max Width | 1300.0 | mn |

GUN MOVEMENTS



IMPORTANT NOTE:

The steppers motors only will be moved if at least one gun channel is enabled and at temperature ready. If not, the motors will not be moved.



- SYMETRICAL MOVEMENT (both motors move at the same time)

Modify the width directly or use the arrows.



- ASYMETRIC MOVEMENT (each motor moves independently)

Modify the width directly or use the arrows.

| 251. | 251.5 mm | | 503.0 mm | | 5 mm | ₽ |
|------|----------|-------|----------|------|------|-------|
| 251. | 5 mm | 503.0 | 0 mm | 251. | 5 mm | CLOSE |
| | | | ▼ | | | |
| | | | | | | |

- LEFT/RIGHT MOVEMENT (moves the application width to the left or right) use the arrows



- CLOSE TOTALLY THE GUN

Press the button CLOSE to the move the gun to "zero" position.

| 251.5 mm | 503.0 mm | 251.5 mm | ✿ |
|----------|----------|----------|-------|
| 251.5 mm | 503.0 mm | 251.5 mm | CLOSE |
| | | | |
| | < > | | |



IMPORTANT NOTE:

If we are working with the pump in "GRAMMAGE MODE" and we want to get the application width directly from the real width of the Procoat, we have to enable the next button in "Grammage" settings page:

| Pump 1 | Pump Control | | |
|-------------------|--------------|-------|--------------|
| Grammage Control | | | |
| Weight Set Point | 10.0 | gr/m2 | |
| Application Width | 10.0 | mm | Get Pro Coat |
| Adhesive Density | 1.00 | g/cc | |
| Fine Tuning | 100.0 | % | |
| Pump Min. Speed | 0.0 | rpm | |
| | | | |

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4.3. PNEUMATIC ADJUSTMENT:



The circuit controlling the vertical movement of the melt plate, and the pressure with which it pushes the melted adhesive, can be adjusted. The injection pressure of air into the drum is factory set and should not be changed.



Cylinders pressure of work adjustment

The minimum pressure of operation is 3 bar. The control is achieved with a regulator.



If the hose issues air and/or the pump cavitates, this is because the pressure of the melt plate is too low. Increase operating pressure until the problem is solved.

Piston movement adjustment:



If one of the pistons moves faster than the other when the plate is switched on, immediately set the plate movement selector to 0 and adjust the cylinders. Before, balance the structure by pushing the higher piston inwards.



This adjustment will be made during an upward movement:

Upward movement adjustment:

1 Adjust the air pressure to 0 bar.



- 2 Turn the position selector as indicated by the \uparrow arrow.
- 3 Press the two ON buttons at the same time.
- **4** Slowly increase the pressure until the melt plate starts to move upwards.
- **5** If the left-hand piston rises at a faster speed, slowly close pneumatic cabinet clip until both pistons are rising at the same speed.



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4.4. PUMP PRESSURE ADJUSTMENT:



The pump pressure will vary depending on the application's requirements. It is adjusted by a nut on the top of the distributor.




4.5. MELT PLATE POSITION ADJUSTMENT:

The position of the melt plate is controlled by three position micro-switches placed in the electric cabinet that are activated by a square bar fixed to the crossbar. The bar goes down with the crossbar and activated the microswitches.

- > Drum entry. It is activated when the melt plate has entered the drum.
- Minimum level. When this level is reached, the drum needs to be \triangleright changed.
- \triangleright Lower stop. It is activated when the plate reaches the bottom of the drum.





CHAPTER 5 OPERATION

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WARNING: This equipment should only be used by qualified personnel who understand all the procedures and are familiar with the necessary safety measures.

5.1. INTRODUCTION:



This chapter explains how to use the equipment.

First of all, make sure that the person operating the machine is duly protected and that all safety instructions are followed. All safety equipment should be in perfect condition.

5.2. UNIT INSTALLATION AND START-UP:



Preparation:

1 Turn the direction selector as indicated by the ↑ arrow and press the two ON buttons at the same time.



- **2** Set the drum in position and secure to the base plate anchoring points.
- 3 Turn the direction selector as indicated by the \downarrow arrow.



- **4** Press the two ON buttons at the same time. Keep them pressed until the melt plate enters the drum.
- 5 Perform the bleed process (see next page)



- 6 Set the motor to one operating mode (manual, auto, grammage, etc.)
- 7 Check that the equipment is correctly adjusted. Readjust if necessary (see Chapter 4)
- 8 The system is ready to run when the ON signal is received.
- **9** The system has two terminals in the main electric cabinet for external on/off signals.



These terminals are factory short-circuited.

The ON order is given by a potential-free contact connecting the two terminals. When the contact is on, the pump will start to run if:

- The equipment is at the correct temperature, the selector is set to manual position and a speed other than zero has been selected.
- The equipment is at the correct temperature, motor control is set to automatic, a speed other than zero has been selected and there is a value in the external line speed 0-5 V input.

There is also a normally open contact and a normally closed contact, both potential-free, to inform the external systems that the equipment is at the correct temperature (see electric diagrams)



Bleed process:

The unit will operate automatically until it is either switched off or the drum is emptied.

If the drum is emptied, the unit signals that the drum needs to be changed.

eed rod

Make sure the equipment is at operating temperature before opening the bleed valves.

<u>sss</u>



- **1** Place a container to collect the glue.
- 2 Set the motor selector to Manual operation.
- **3** Open bleed valve and wait for the hot melt to come out.
- 4 As soon as it does, close bleed valve 1.
- **5** Turn the motor selector to 0.

Now there is no air in the adhesive circuit.





The pump only works when the position selector is set to \downarrow and the equipment has reached the minimum operating temperature.

If the adhesive used reacts to air (PUR, for instance), cover bleed valves 1 and 2 with high-temperature lubricant to prevent air from entering, degrading and blocking them.

5.3 DRUM CHANGE:



Change the drum as follows:

- 1 Turn the position selector as indicated by the \uparrow arrow.
- 2 Press the two ON buttons at the same time.
- **3** The plate moves upwards. Air is introduced in the drum to prevent a vacuum from forming.
- **4** When the plate reaches the top, the system shuts down and the drum can be changed.
- **5** Position the tray to collect drops of glue and protect against burns.
- 6 Change the drum and repeat procedure 5.2 "Unit installation and start-up"



Make sure that the bleed valve is closed when the plate moves upward.



5.4. SHUT-DOWNS:

There are two possible types of shut-down:

Pump shut-down:

If you wish the pump to shut down, set the motor selector to 0.

The temperature control will maintain the machine's temperature.



If the pump is to be shut down for some time, we recommend switching on the Low Maintenance function.

Total shut-down:

To shut down the entire machine, switch off at the main switch.



If the machine is to be shut down for some time, we recommend removing the drum and cleaning the equipment. Leave the melt plate in its lowest position.

Daily procedure:



At the end of the day, before the machine is switched off, bleed the equipment following the instructions provided in the "Bleed process" section.



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CHAPTER 6 MAINTENANCE

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WARNING: The maintenance operations described in this chapter should only be performed by qualified personnel understanding the processes and familiar with the safety measures involved.

6.1. INTRODUCTION:

This chapter contains the procedures involved in the maintenance of the follower plate. These maintenance procedures guarantee safe operations and increase the life of the follower plate. Before starting a maintenance operation, carefully read chapter 1 Safety.



First of all, make sure that you are duly protected and follow all pertinent safety measures:

1º Switch off the air at the mains.

2º Switch off the main switch.

3º Lock the main switch in place.

- 4º Make sure that the power is off.
- **5°** Follow all applicable safety standards.

6.2. MAINTENANCE RECOMMENDATIONS:

The following table shows the frequency with which maintenance operations should be performed:

| Frequency | Maintenance |
|-----------------|---|
| | Clean the outer surface of the unit |
| Daily Weekly | Inspect all the electric, pneumatic and hydraulic connections. Replace or repair when necessary |
| | Check the condition of the melt plate gasket. Make sure it is free from glue |
| | Check the condition of the position micro-switches. They should be clean and free from glue. |
| | Bleed the air filter |
| | Check the condition of the pneumatic cylinders and the drum melter structure |
| | Clean the motor ventilation cover |
| When necessary | Change the air regulator filter |



6.3. MAINTENANCE PROCESSES:

Cleaning the equipment



Vacuum the dust or glue remains or remove with a soft cloth, especially from the distributor, bleed valves and melt plate.

After bleeding, clean the distributor to prevent glue from entering the electric connection box.

Clean the control panel periodically with a soft cloth. Do not use solvents which could rust the controls.

Use a soft cloth to remove dust and glue remains from the position microswitches



If you use a cleaning agent, make sure that it is compatible with the adhesive being employed. In case of doubt, contact the glue manufacturer.

Motor:

Remove dust from the motor ventilation cover with a cloth.

Bleeding the air filter:

Press the button at the bottom of the air filter.

The change of the regulator filter will be done when necessary, depending on the dirt entrained in the pneumatic network.



Melt plate:

Check that the melt plate gasket is in good condition; if not, change it.

If the melt plate is soiled with glue, clean with a cloth or a cleaning agent to prevent adhesive from entering the electric connection box.

The fins of the melt plate radiator must be cleaned with a cloth once the drum is removed.



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CHAPTER 7 EQUIPMENT REPAIR GUIDE

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WARNING: The maintenance operations described in this chapter should only be performed by qualified personnel understanding the processes and familiar with the safety measures involved.

7.1. INTRODUCTION:

This chapter refers to the most common faults in your equipment.

Breakdowns occur when the flow of glue is reduced or stops, or the alert system informs of a fault. Try to solve the problem with the help of this manual.

If the problem cannot be solved with the information provided here, contact your Melton representative.

7.2. MECHANICAL FAULTS:











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7.3. ELECTRICAL FAULTS:















7.4. ADHESIVE APPLICATION PROBLEMS:



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CHAPTER 8 EQUIPMENT REPAIR GUIDE

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WARNING: The maintenance operations described in this chapter should only be performed by qualified personnel understanding the processes and familiar with the safety measures involved.

8.1. INTRODUCTION:



This chapter describes the procedures to remove and change some components. These procedures should be followed during maintenance or repair operations.

First of all, make sure that you are duly protected and follow all safety instructions:

1º Close the air supply to the unit.

- 2º Switch off and isolate the unit.
- **3º** Protect the main switch with a key to avoid reconnections
- 4º Check that the unit is not energized.
- **5°** Follow applicable safety and health standards.

Chapter 9 includes lists of the parts to which the procedures refer.

8.2. CHANGING THE PUMP:

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Pump removal:



Wear long sleeves and protective gloves and use a face shield, to prevent burns from the hot glue.

1 Heat the equipment, with the motor control set to zero, until the glue has melted. Then switch off the machine.





- **2** Use the bleed valves to bleed the system, removing all residual pressure.
- **3** Loosen the screw attaching the pump to the coupling and remove it.

- 4 Remove the screws attaching the pump to the distributor.
- **5** Take the pump to a clean table for dismantling.
- 6 Clean all parts carefully.





If you use a cleaning agent, make sure that it is compatible with the adhesive being used. In case of doubt, contact the glue manufacturer.

Gear pump assembly instructions:



Follow the assembly instructions carefully. The position and alignment of some of the parts are critical for the pump operation.

- 1 Inspect all the pump parts for wear or damage. Change the pump if necessary.
- 2 Attach the pump assembly to the distributor with the screws.
- 3 Place the coupling and tighten screw.

8.3. REPAIRING THE DISTRIBUTOR:



Proceed as follows to change the heating element and/or temperature sensor.

First of all, clean the outside of the distributor to prevent adhesive from entering the electric system (see 6.3)

- 1° Unscrew the electric cap and remove, taking care not to damage the electric wiring.
- **2º** Remove the heating element and/or temperature sensor. If it is stuck, push from the other side of the housing.
- **3°** Disconnect the heating element and/or temperature sensor from the terminal.
- 4° Connect the new heating element and/or probe according to the electric diagram. Assemble in reverse order.



8.4. REPAIRING THE PRESSURE REGULATOR:



Proceed as follows to remove / install the regulator.

- 1º Open the bleed valves to remove all residual pressure.
- 2º Loosen the regulator screws with a number 5 Allen key and remove the cover.
- 3º Remove the regulator with pliers.
- **4°** Dismantle the regulator by pushing the spring needle system from the hole in the tip.
- 5° Clean all the components and replace faulty ones.



If you use a cleaning agent, make sure that it is compatible with the adhesive employed. In case of doubt, contact the adhesive manufacturer.

6° Assemble in reverse order. Change the O-rings and install new ones covered in high temperature lubricant.



8.5. REPAIRING THE MELT PLATE:

Melt plate repairs include electric parts such as the heating element, temperature sensor and/or safety thermostat, and replacement of the plate gasket.

Electric repair:



Before starting to repair the melt plate, clean it to prevent adhesive from entering the electric connection box (see 6.3)

- 1° Switch off the machine at the mains.
- 2º Unscrew the electric cover and remove it.



- **4°** Disconnect the heating element and/or temperature sensor from the terminal.
- 5° Connect the new heating element and/or sensor according to the electric diagram.
- **6°** Assemble in reverse order. If you have removed the radiator, reinstall ensuring that the air injector is correctly positioned.

Replacing the melt plate gaskets:

- 1° Switch off the machine at the mains.
- 2º The plate has to be supported by a wooden wedge
- 3º Disconnect the air circuit from the air injector plugs.
- 4º Loosen the gaskets.
- **5°** Loosen the screws and lift the crossbar enough to insert the gaskets.
- 6° Grease the gaskets with high-temperature lubricant and install.
- 7º Put the gaskets in position and screw down.
- **8°** Slowly and carefully lower the crossbar over the cylinders until the bars are positioned and screw down.
- 9° Connect the air circuit to the air injector plugs.





8.6. REPAIRING THE PNEUMATIC REGULATION SYSTEM:



The equipment has two independent circuits. One controls the movement of the melt plate and the other controls the valve injecting air into the drum when the melt plate is going to be removed from the drum.

If one of these parts becomes worn and needs replacing, see the part listings in chapter 9 and the pneumatic circuit diagrams in chapter 10.

All these operations should be performed with the machine disconnected from the main air system, and only after bleeding and depressurising the equipment.

Remember that when there is no pressure in the pneumatic cylinders, the melt plate will fall, and it may fall faster on one side, stopping before reaching the bottom, if the movement is not correctly adjusted (see chapter 4 on machine adjustments).



8.7. REPAIRING THE AIR INJECTION SYSTEM:



Below are the instructions for the assembly / disassembly of the air injector.

Disassembly:

- 1º Disconnect the machine from the air circuit.
- 2º Release the air intake pipes from the plugs.



Be careful with air release. The system is under 1 bar of pressure (this pressure is adjusted by a regulator located inside the pneumatic cabinet; it is adjusted when supplied and should not be modified, since it would inject air with too much pressure and could destroy the drum)

- 3º Loosen the screws and remove the air injector.
- 4º The injector consists of a cut-off module which closes on a seating located at the end of a telescopic tube. To disassemble for cleaning, remove the tip from its position and unscrew both the telescopic tube and the cut-off module air plugs.
- 5° Clean all the components and replace if faulty.

Assembly: Follow the above procedure in reverse order. Use new O-rings lubricated with high-temperature grease.



8.8. REPAIRING THE BLEED VALVE:

If the bleed valve is blocked, proceed as follows:





- 1º Heat the machine, with the motor control set to zero, until the glue has melted. Then switch off the machine.
- 2º To prevent glue from splashing when you clean the valve, make sure that there is no pressure in the circuit. Work with the pressure adjusted to the lowest value, with no pressure in the drum.
- **3°** Open the blocked valve. Check that the operating mechanism is in working order and that it opens when the key is turned.
- 4º Insert a rod, with a maximum diameter of 6 mm, and remove the obstruction. (Usually, it will be degraded glue. Break it with the rod)
- 5° Continue until all the glue has been removed.

If the valve is faulty, it will need to be removed.



- 1º Heat the machine, with motor control set to zero, until the glue has melted. Then switch off the machine
- 2º Loosen and remove the key screw.
- **3°** Loosen the lower socket of the key rod and then unscrew the rod with a 7 mm spanner.
- 4° Release the cock with a 17 mm spanner.
- 5° Clean all the components and replace if faulty.
- 6º Assemble in reverse order

8.9. REPAIRING ELECTRIC COMPONENTS:



If one of the electric components needs to be repaired, proceed according to the part listings and the electric diagrams.

All these operations should be performed with the machine switched off at the mains and disconnected from the main air circuit, making sure that the system has been duly bled and depressurised.



ANNEX A LOG SHEETS

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| DATE | INCIDENCE |
|------|-----------|
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ANNEX B COMMUNICATIONS

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B.1. INTRODUCTION

As we can see in the point *4.2.5.7 Communications* we can use the communications to control the equipment from another machine or for monitoring alarms signals and process values of the variables.

For it, we can use diferent communications protocols, which will be explained in the next points.

The melter always will be the slave, and the main machine will be the master.

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B.2. PROTOCOLS

B.2.1. MODBUS TCP

B.2.1.1. HARDWARE

There is not any specific module to communicate using Modbus TCP communication. To do it, we will use the RJ45 connector in the touch screen.



MAIN MACHINE

D.2.1.2. INTERFACE CONFIGURATION

This Modbus communication protocol is configured for exchanging data using *Write Holding Registers* and *Read Input Registers.*

Write Holding Registers

The client PLC (main machine PLC) will use this function to write values in the server (melter PLC).

| Variable | Mapping | Channel | Address | Туре | Default Value | Unit | Description |
|---------------------------------------|---------|----------------------|---------|--------------------|---------------|------|-------------------------|
| B- 🍫 | | Holding Registers | %IW105 | ARRAY [07] OF WORD | | | |
| 😟 - 🍫 | | Holding Registers[0] | %IW105 | WORD | | | MelterControl & Command |
| ÷-* | | Holding Registers[1] | %IW106 | WORD | | | DataIndex |
| ÷ * | | Holding Registers[2] | %IW107 | WORD | | | ChannelNumber |
| ⊕- * ≱ | | Holding Registers[3] | %IW108 | WORD | | | WiteDataValue |
| 🕀 - 🍫 | | Holding Registers[4] | %IW109 | WORD | | | LineSpeed1 |
| 🕀 🦘 | | Holding Registers[5] | %IW110 | WORD | | | LineSpeed2 |
| ⊕- * ≱ | | Holding Registers[6] | %IW111 | WORD | | | LineSpeed3 |
| · · · · · · · · · · · · · · · · · · · | | Holding Registers[7] | %IW112 | WORD | | | LineSpeed4 |

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Read Input Registers

The client PLC (main machine PLC) will use this function to read values from the server (melter PLC).

| Variable | Mapping | Channel | Address | Type | Default Value | Unit | Description |
|---------------|---------|--------------------|---------|--------------------|---------------|------|------------------|
| * * | | Holding Registers | %IW105 | ARRAY [07] OF WORD | | | |
| - ** | | Input Registers | %QW380 | ARRAY [08] OF WORD | | | |
| 18 5 0 | | Input Registers[0] | %QW380 | WORD | | | Status |
| · · · | | Input Registers[1] | %QW381 | WORD | | | AckDataIndex |
| 4- 5 0 | | Input Registers[2] | %QW382 | WORD | | | AckChannelNumber |
| 10 Top | | Input Registers[3] | %QW383 | WORD | | | ReadDataValue1 |
| 16 Top | | Input Registers[4] | %QW384 | WORD | | | ReadDataValue2 |
| ······ | | Input Registers[5] | %QW385 | WORD | | | ReadDataValue3 |
| · · · · | | Input Registers[6] | %QW386 | WORD | | | ReadDataValue4 |
| ÷ ** | | Input Registers[7] | %QW387 | WORD | | | ReadDataValue5 |
| * ** | | Input Registers[8] | %QW388 | WORD | | | ReadDataValue6 |

This configuration has to be made in client PLC to be able to communicate:

| Watchdog | 500 | - | (ms) | Close TCP socket |
|---|----------------------|---|--------|------------------|
| lave port | 502 | + | Bind t | to adapter |
| olding registers | 8 | * | (%IW) | Writeable |
| nput registers | 9 | - | (%QW) | |
|] Discrete Bit Areas | 0 | | | 4 |
| oils | 0 | * | (%DX) | |
| | | | | |
| iiscrete Inputs | 0 | 4 4 | (%QX) | |
| ata Model | 0 | Ŧ | (%QX) | |
| ata Model tartaddresses | 0 | ÷ | (%QX) | |
| lata Model tartaddresses Coils | 0 | * | (%QX) | |
| ata Model tart addresses Coils Discrete inputs | 0 | * | (%QX) | |
| ata Model tart addresses Coils Discrete inputs Holding register | 0 0 0 24576 | 4 • • • • • • • • • • • • • • • • • • • | (%QX) | |

If needed, Valco Melton has examples for communicating with Siemens and B&R.



B.2.2. OPCUA

B.2.2.1. HARDWARE

There is not any specific module to communicate using OPC UA communication. To do it, we will use the RJ45 connector in the touch screen.



MAIN MACHINE

B.2.2.2. INTERFACE CONFIGURATION

We can use UAExpert program to watch the Identifier of the Variables and the Namespace Index.

| # | Server | Node Id | Display Name | Value | Datatype |
|----|--------|---|------------------|-------|----------|
| 1 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.ChannelNumber | ChannelNumber | 0 | UInt16 |
| 2 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.Command | Command | 0 | UInt16 |
| 3 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.DataIndex | DataIndex | 0 | UInt16 |
| 4 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed1 | LineSpeed1 | 0 | UInt16 |
| 5 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed2 | LineSpeed2 | 0 | UInt16 |
| 6 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed3 | LineSpeed3 | 0 | UInt16 |
| 7 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed4 | LineSpeed4 | 0 | UInt16 |
| 8 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.MelterControl | MelterControl | 0 | UInt16 |
| 9 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.WriteDataValue | WriteDataValue | 0 | UInt16 |
| 10 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.AckChannelNumber | AckChannelNumber | 0 | UInt16 |
| 11 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.AckDataIndex | AckDataIndex | 0 | UInt16 |
| 12 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue1 | ReadDataValue1 | 0 | UInt16 |
| 13 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue2 | ReadDataValue2 | 0 | UInt16 |
| 14 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue3 | ReadDataValue3 | 0 | UInt16 |
| 15 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue4 | ReadDataValue4 | 0 | UInt16 |
| 16 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue5 | ReadDataValue5 | 0 | UInt16 |
| 17 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue6 | ReadDataValue6 | 0 | UInt16 |
| 18 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.Status | Status | 0 | UInt16 |



| Attribute | Value |
|-------------------------|---|
| ✓ Nodeld | Nodeld |
| NamespaceIndex | 4 |
| IdentifierType | String |
| Identifier | [var]EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.Status |
| NodeClass | Variable |
| BrowseName | 4, "Status" |
| DisplayName | "en-Us", "Status" |
| Description | BadAttributeIdInvalid (0x80350000) |
| Write/Mask. | BadAttributerdInvalla (0x80350000) |
| UserW)(teMask | BadAttributeIdInvalid (0x80.150000) |
| ✓ Value | |
| SourceTimestamp | 04/08/2022 14:31:15.351 |
| SourcePicoseconds | 0 |
| ServerTimestamp | 04/08/2022 14:31:15.348 |
| ServerPicoseconds | 0 |
| StatusCode | Good (0x00000000) |
| Value | 24 |
| ✓ DataType | UInt16 |
| NamespaceIndex | 0 |
| IdentifierType | Numeric |
| Identifier | 5 |
| ValueRank | -1 |
| ArrayDimensions | (JadAttributeIdInvalid (0x60350000) |
| AccessLevel | CurrentRead, CurrentWrite |
| UserAccessLevel | CurrentRead, CurrentWrite |
| MinimumSamplingInterval | 100 |
| Historizing | false |

The opc ua port is **4840**. There is not security. NamespaceIndex: **4**. The URL is: **opc.tcp://10.24.91.135**

10.24.91.135 is the IP Address of the melter PLC.

Variable's name:

| # | Server | Node Id | Display Name | Value | Datatype |
|----|--------|---|------------------|-------|----------|
| 1 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.ChannelNumber | ChannelNumber | 0 | UInt16 |
| 2 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.Command | Command | 0 | UInt16 |
| 3 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.DataIndex | DataIndex | 0 | UInt16 |
| 4 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed1 | LineSpeed1 | 0 | UInt16 |
| 5 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed2 | LineSpeed2 | 0 | UInt16 |
| 6 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed3 | LineSpeed3 | 0 | UInt16 |
| 7 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.LineSpeed4 | LineSpeed4 | 0 | UInt16 |
| 8 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.MelterControl | MelterControl | 0 | UInt16 |
| 9 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataReceive_Frame.WriteDataValue | WriteDataValue | 0 | UInt16 |
| 10 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.AckChannelNumber | AckChannelNumber | 0 | UInt16 |
| 11 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.AckDataIndex | AckDataIndex | 0 | UInt16 |
| 12 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue1 | ReadDataValue1 | 0 | UInt16 |
| 13 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue2 | ReadDataValue2 | 0 | UInt16 |
| 14 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue3 | ReadDataValue3 | 0 | UInt16 |
| 15 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue4 | ReadDataValue4 | 0 | UInt16 |
| 16 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue5 | ReadDataValue5 | 0 | UInt16 |
| 17 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.ReadDataValue6 | ReadDataValue6 | 0 | UInt16 |
| 18 | Exor | NS4 String var EXOR-ARM-Linux.Application.OPCUA.DataSend_Frame.Status | Status | 0 | UInt16 |

IMPORTANT NOTE

The master needs to send a 1 Hz clock in Melter Control bit 7:

|var|EXOR-ARM-LINUX.Application.OPCUA.DataRecieve_Frame.MelterControl.7

If not an error of communication will appear.



B.3. COMMUNICATION DATA LIST

B.3.1. INTRODUCTION

Data exchange between master and slave will be done using indexes (*Data Index*). In this way, we only send a small data block with the information ordered, so we avoid overload the bus with unnecessary data.

For example, if the master wants to read the pump speed of the pump, it has to send a data block to the FLEXDRUM. After that, FLEXDRUM will send back a data block which contains the information ordered by the master.



B.3.2. COMMUNICATION DATA BLOCKS

B.3.2.1. Send Data Block

This data block will be sent from master the slave.

If we are using **OpcUa** communication, the length of the data block will be 18 bytes:

| Ser | Send Data Block (master 🔿 slave) | | | | | |
|----------------|----------------------------------|------------------------------|--|--|--|--|
| Byte Direction | Format | Description | | | | |
| Byte 0 + 1 | Word | Melter Control | | | | |
| Byte 2 + 3 | Word | Command | | | | |
| Byte 4 + 5 | Word | Data index | | | | |
| Byte 6 + 7 | Word | Channel number | | | | |
| Byte 8 + 9 | Word | Write data value | | | | |
| Byte 10 + 11 | Word | Line speed value for motor 1 | | | | |
| Byte 12 + 13 | Word | Line speed value for motor 2 | | | | |
| Byte 14 + 15 | Word | Not Used | | | | |
| Byte 16 + 17 | Word | Not Used | | | | |

Else, 16 bytes:

| Send Data Block (master 🗲 slave) | | | | | |
|----------------------------------|--------|------------------------------|--|--|--|
| Byte Direction | Format | Description | | | |
| Byte 0 | Byte | Melter Control | | | |
| Byte 1 | Byte | Command | | | |
| Byte 2 + 3 | Word | Data index | | | |
| Byte 4 + 5 | Word | Channel number | | | |
| Byte 6 + 7 | Word | Write data value | | | |
| Byte 8 + 9 | Word | Line speed value for motor 1 | | | |
| Byte 10 + 11 | Word | Line speed value for motor 2 | | | |
| Byte 12 + 13 | Word | Not Used | | | |
| Byte 14 + 15 | Word | Not Used | | | |



B.3.2.2. Receive Data Block

This data block will be sent from slave the master. The length of the data block will be 18 bytes.

| Reco | Receive Data Block (slave ᢣ master) | | | | | |
|----------------|-------------------------------------|-----------------------------|--|--|--|--|
| Byte Direction | Format | Description | | | | |
| Byte 0 + 1 | Word | Status | | | | |
| Byte 2 + 3 | Word | Acknowledge: Data index | | | | |
| Byte 4 + 5 | Word | Acknowledge: Channel number | | | | |
| Byte 6 + 7 | Word | Read data value 1 | | | | |
| Byte 8 + 9 | Word | Read data value 2 | | | | |
| Byte 10 + 11 | Word | Read data value 3 | | | | |
| Byte 12 + 13 | Word | Read data value 4 | | | | |
| Byte 14 + 15 | Word | Read data value 5 | | | | |
| Byte 16 + 17 | Word | Read data value 6 | | | | |

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Melter Control

With this register we can control the melter given signals by communications.

| Bit | Value | Action |
|------|----------|-----------------------------------|
| ₀₅₫¹ | | Rising edge: Heat ON |
| 0 | ¹ᡶ₀ | Falling edge: Heat OFF |
| 1 | 1 | Reset Alarms |
| L | 0 | No Reset Alarms |
| 2 | 1 | Enable Pump 1 |
| Z | 0 | Disable Pump 1 |
| 2 | 1 | Enable Pump 2 |
| 5 | 0 | Disable Pump 2 |
| 4 | ₀₫ | Rising edge: Stop ProCoat motors |
| 5 | ₀₁ | Rising edge: Close ProCoat motors |
| G | ₀₫¹ | Rising edge: Switch on Standby |
| O | ¹ᡶ₀ | Falling edge: Switch off Standby |
| 7 | Send a 1 | .HZ clock as watchdog. |

IMPORTANT NOTE



If we works by COMMUNICATIONS, the "Pump enable" (see point 3.7) signal always should be connected, because it works as SAFE TORQUE OFF input.

Then, you also will enable the pump using the communication register (Melter Control bit 2 (pump 1) and Melter Control bit 3 (pump 3)



• Command

 The master will send a command to melter. It has to be one of these:

Command = 1 (dec) = No data exchange Command = 3 (dec) = Read data from the slave Command = 6 (dec) = Write data in the slave

- Command = 0 is inadmissible and the rest of the values will be interpreted as a protocol fault in *Status* variable in the reception data block.

• Data index

- It is used for addressing a data communication to send or receive. The value to be taken in each case depends on the value we want to read or write.
- If the *Acknowledge Data Index* of the reception data block is the same that the *Data Index*, the order will be completed.
- Data Index equal to zero is interpreted as no data exchange.

Channel number

- It is used for indicate the channel which we want to read or write, for example, a temperature channel, pressure channel, motor data, etc.
- Starting with the channel number specified in this parameter, the order will be made for writing or reading the data for the 6 channels next.
- If *Acknowledge channel number* of Reception Data Block is equal to *Channel Number* of Send Data Block, the order will be finished.
- Channel number equal to zero is interpreted as No Channel Number, and it will be used for melter data.

• Write Data Value

In writing orders, the master will write this value in the slave parameter indicated by data index and channel number.



• Line Speed Value for motor 1-n

- This variable will be sent with all data block, independently if there is a *Command* 1,3 o 6.
- It corresponds with the "Line Speed Signal (0-10V)".
- The values will be defined from 0.0 to 100.0%, and it is necessary to multiply by 10. For example:
 - \circ If you want to send 10.00V \rightarrow you have to write 1000
 - \circ If you want to send 5.23V \rightarrow you have to write 523



B.3.4. RECEIVE DATA BLOCK

• Status

- This variable indicates us the status of the equipment.

| Bit | Value | Action | | | | | |
|-----|------------------|--|--|--|--|--|--|
| | 1 | System Ready | | | | | |
| 0 | | System Not Ready | | | | | |
| 1 | | Not Used | | | | | |
| 2 | 1 System Warning | | | | | | |
| 2 | 0 | System Not Warning | | | | | |
| 2 | 1 | System Fault | | | | | |
| 3 | 0 | System Not Fault | | | | | |
| 4 | 1 | System On | | | | | |
| 4 | 0 | System Off | | | | | |
| - | 1 | System Heating | | | | | |
| 5 | 0 | System Not Heating | | | | | |
| 6 | 1 | System Standby Heating Mode | | | | | |
| 6 | 0 | System Normal Heating Mode | | | | | |
| _ | 1 | Pump 1 Running | | | | | |
| / | 0 | Pump 1 Stopped | | | | | |
| • | 1 | Pump 2 Running | | | | | |
| 8 | 0 | Pump 2 Stopped | | | | | |
| • | 1 | Procoat – Gun Steppers in Movement | | | | | |
| 9 | 0 | Procoat – Gun Steppers Stopped | | | | | |
| 10 | 1 | Drum Low Level | | | | | |
| 10 | 0 | Drum Not Low Level | | | | | |
| 11 | 1 | Drum Empty Level | | | | | |
| | 0 | Drum Not Empty Level | | | | | |
| 12 | | Not Used | | | | | |
| 13 | | Not Used | | | | | |
| | 1 | Communication Protocol Fault | | | | | |
| | | Command wrong | | | | | |
| 14 | | Data Index wrong | | | | | |
| | | Channel Number wrong | | | | | |
| | 0 | Communication Protocol No Fault | | | | | |
| | 1 | Communication Data Fault | | | | | |
| | | Writing order in "Standard" melter control mode | | | | | |
| 15 | | Order for channels not installed | | | | | |
| 12 | | Writing value out of range | | | | | |
| | | Writing order for variables which only can be read | | | | | |
| | 0 | Communication Data No Fault | | | | | |

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Acknowledge: Data index

- If the *Acknowledge Data Index* of the reception data block is the same that the *Data Index*, the order will be completed.
- Acknowledge: Channel number
 - If *Acknowledge Channel Number* of Reception Data Block is equal to *Channel Number* of Send Data Block, the order will be finished.
- Read Data Value n
 - In this register, the master read the values sent by the slave.

We read up to 6 values at the same time, that is the reason why we have the parameters *Read Data Value 1* to *Read Data Value 6*.

For example, if we send the command to read "Temperature Actual" of hose 1, we will receive the values of 1 to 6.

However, if we send the command to read the parameter "*Waiting Time*", we only will receive one value in *Read Data Value 1*. That is why we don't have 6 values of "waiting time" parameters, so only we can read one.

B.3.5. EXAMPLES

Example 1: master writes 45 minutes in the parameter "Waiting Time" (Data Index = 9) in the melter.

| Data index | Channel number | Write data value |
|------------|----------------|------------------|
| 9 | 0 | 45 (dec) |

Example 2: master writes 50.5 rpm in the parameter "MANUAL MODE - Pump Speed Set Point" (Data Index = 32) in the pump 1.

| Data index | Channel number | Write data value |
|------------|----------------|------------------|
| 32 | 1 | 505 (dec) |



Example 3: master reads the parameter "Temperature Actual Value" (Data Index = 120) in the channel 3.

| Data index | Channel number | Read data value |
|------------|----------------|-------------------|
| | 3 | 150 (dec) [150ºC] |
| | 4 | 152 (dec) [152ºC] |
| 120 | 5 | 161 (dec) [161ºC] |
| 120 | 6 | 162 (dec) [162ºC] |
| | 7 | 170 (dec) [170ºC] |
| | 8 | 185 (dec) [185ºC] |

Example 4: master sets a wrong value in the parameter Data Index, so all read data values are fixed to zero.

| Data index | Data index Channel number Re | |
|------------|------------------------------|---|
| | | 0 |
| | | 0 |
| 000 | | 0 |
| 999 | | 0 |
| | | 0 |
| | | 0 |

Example 5: Read Data Values invalid will be fixed to zero.

For example, if we want to read the parameter "*Pump Speed Actual Value*" (Data Index = 36) of one equipment with 2 pumps, the *Read Data Values* of the pumps not installed will be fixed to zero.

| Data index | Channel number | Read data value |
|------------|----------------|----------------------|
| | 1 | 152 (dec) [15,2 rpm] |
| | 2 | 152 (dec) [15,2 rpm] |
| 26 | No motor | 0 |
| 30 | No motor | 0 |
| | No motor | 0 |
| | No motor | 0 |



B.3.6. COMMUNICATION DATA LIST

In the next tables we will see all variables which act in the control of the B50 G3. We can distinguish two data types:

- Read (R): the data only can be read.
- Write (W): the data only can be written.
- Read and Write (R/W): the data can be read and written.

The data which decimal separator has to be multiplied or divided by a factor:

- The data with one number after decimal separator, has to be multiplied or divided by 10.
- The data with two numbers after decimal separator, has to be multiplied or divided by 100.
- The data with three numbers after decimal separator, has to be multiplied or divided by 1000.

For the variables which aren't related to any temperature or pump channel, we will use the *Channel Number* 0.



D.3.6.1. Melter Data

| Data Index | Read & Write | | Data Values | Channel Number | Limits | |
|---------------|-----------------|--------|-----------------------------|-------------------|---------------------|--|
| | | Melter | Control Mode | | 0 - 2 | |
| 1 | р | 0 | Standard | _ | | |
| 4 | n. | 1 | Communications | 0 | | |
| | | 2 | Dual | | | |
| | | Melter | Status | | | |
| | | 1 | System Heating | | | |
| | | 3 | System Ready | | | |
| | | 5 | System Warning | | 0 - 20 | |
| | | 6 | System Fault | | | |
| 10 | R | 7 | System OFF | 0 | | |
| | | 8 | Standby | | | |
| | | 14 | Drum Out | | | |
| | | 19 | Selector NOT in UP position | | | |
| | | 20 | Drum Low Level Warning | | | |
| | | 23 | Drum Empty Warning | | | |
| | | Alarms | Summary | | | |
| | | Bit 0 | Melter Alarm | | | |
| 22 | Р | Bit 1 | Temperature Alarm | 0 | | |
| 25 | n | Bit 2 | Motor Alarm | 0 | - | |
| | | Bit 3 | Pressure Alarm | | | |
| | | Bit 4 | Tank Level Alarm | | | |
| | | Conne | ct / Disconnect Timing | | | |
| 200 | R/W | 0 | Disabled | 0 | 0 - 1 | |
| | | 1 | Enabled | | | |
| 90 | R/W | Adhesi | ve Density | 0 | 0.00 - 10.00 gr/cm3 | |

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B.3.6.2. Pumps Data

Depending on the number of pumps the channel number will be different. So, in the next table we can see the relationship between the *"Channel Number"* parameter and pump.

| Channel Number | Pump Channel |
|-------------------|--------------|
| 1 | Pump 1 |
| 2 | Pump 2 |

• Common Data

| Data Index | Read & Write | | Data Values | Channel Number | Limits |
|---------------|-----------------|------|-------------------------------|-------------------|-----------------|
| | | Pum | p Working Mode | | |
| | | 0 | Automatic | 1-2 | 0 - 4 |
| 30 | R/W | 2 | Grammage | | |
| | | 3 | Grams Per Product | | |
| | | 4 | Manual | | |
| 33 | R/W | Anal | ogical Input High Value | 1-2 | 0.0 – 10.00 V |
| 39 | R/W | Anal | ogical Input Low Value | 1-2 | 0.0 – 10.00 V |
| 40 | R/W | Anal | Analogical Input Offset Value | | 0.0-10.00 V |
| 36 | R | Pum | p Speed Actual Value | 1-2 | 0.0 - 100.0 rpm |

• Manual Mode

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|------------------------------------|-------------------|-----------------|
| 32 | R/W | MANUAL MODE - Pump Speed Set Point | 1-2 | 0.0 - 100.0 rpm |

Automatic Mode

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|--|-------------------|------------------|
| 34 | R/W | AUTOMATIC MODE - Pump Speed Scaled Max. Value | 1-2 | 0.0 - 100.00 rpm |
| 35 | R/W | AUTOMATIC MODE - Pump Speed Scaled Min. Value | 1-2 | 0.0 - 100.00 rpm |
| 37 | R/W | AUTOMATIC MODE - Pump Speed Min. Value | 1-2 | 0.0 - 100.00 rpm |



Grammage Mode

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|--|-------------------|------------------------|
| 94 | R/W | GRAMMAGE MODE - Set Point (gr/m2) | 1-2 | 0.00 - 1000.0 gr/m2 |
| 327 | R/W | GRAMMAGE MODE - Application Width | 1-2 | 0 - 6000.0 mm |
| 91 | R/W | Fine Tuning | 1-2 | 0.0 - 200.0 % |
| 46 | R/W | GRAMMAGE MODE - Line Speed Min. Value (m/min) | 1-2 | 0 - 5000.0 m/min |
| 326 | R/W | GRAMMAGE MODE - Line Speed Max. Value (m/min) | 1-2 | 0 – 5000.0 m/min |
| 390 | R | GRAMMAGE MODE - Actual Line Speed (m/min) | 1-2 | 0 - 5000.0 m/min |
| 50 | R/W | GRAMMAGE MODE – Pump Speed Minimum Value | 1-2 | 0.0 - 100.0 rpm |

• Grams Per Product Mode

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|---|-------------------|------------------------|
| 325 | R/W | GPP MODE - Set Point (grams/product) | 1-2 | 0.001 – 60.000 gr/p |
| 48 | R/W | GPP MODE - Line Speed Min. Value (prod/min) | 1-2 | 0 - 60000 prod/min |
| 328 | R/W | GPP MODE - Line Speed Max. Value (prod/min) | 1-2 | 0 - 60000 prod/min |
| 391 | R | GPP MODE - Actual Line Speed (prod/min) | 1-2 | 0 - 60000 prod/min |
| 49 | R/W | GPP MODE - Pump Speed Minimum Value | 1-2 | 0.0 - 100.0 rpm |
| 91 | R/W | Fine Tuning | 1-2 | 0.0 - 200.0 % |



• Pressure Control Mode

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|--|-------------------|---------------|
| 61 | R | Actual Pressure Transducer 1 | 1-2 | 0 - 100.0 Bar |
| 64 | R/W | PRESSURE CONTROL - Set Point | 1-2 | 0 - 100.0 Bar |
| 65 | R/W | PRESSURE CONTROL - PID Kp | 1-2 | 0.00 - 650.00 |
| 66 | R/W | PRESSURE CONTROL - PID Tn | 1-2 | 0.00 - 650.00 |
| 67 | R/W | PRESSURE CONTROL - PID Tv | 1-2 | 0.00 - 650.00 |
| 70 | R/W | PRESSURE CONTROL - Low Warning Value (ΔSP) | 1-2 | 0 - 100.0 Bar |
| 72 | R/W | PRESSURE CONTROL - Low Fault Value (ΔSP) | 1-2 | 0 - 100.0 Bar |
| 73 | R/W | PRESSURE CONTROL - High Warning Value (ΔSP) | 1-2 | 0 - 100.0 Bar |
| 76 | R/W | PRESSURE CONTROL - High Fault Value (ΔSP) | 1-2 | 0 - 100.0 Bar |
| 147 | R/W | PRESSURE CONTROL - Start Up Time Fault Delay | 1-2 | 0 - 65000 seg |
| 148 | R/W | PRESSURE CONTROL - Working Time Fault Delay | 1-2 | 0 - 65000 seg |

• Pressure Supervision Mode

| Data Index | Read & Write | | Data Values | Channel Number | Limits |
|---------------|-----------------|------|--|-------------------|---------------|
| | | PRES | PRESSURE SUPERVISION - Enable | | |
| 69 | R/W | 0 | Disable | 1-2 | 0 - 1 |
| | | 1 | Enable | | 2 0 100 0 Per |
| 71 | R/W | PRES | SURE SUPERVISION - Low Warning Value | 1-2 | 0 - 100.0 Bar |
| 74 | R/W | PRES | SURE SUPERVISION - High Warning Value | 1-2 | 0 - 100.0 Bar |
| 75 | R/W | PRES | SURE SUPERVISION - Low Fault Value | 1-2 | 0 - 100.0 Bar |
| 77 | R/W | PRES | SURE SUPERVISION - High Fault Value | 1-2 | 0 - 100.0 Bar |
| 199 | R/W | PRES | SURE SUPERVISION - Start Up Time Fault Delay | 1-2 | 0 - 65000 sec |
| 149 | R/W | PRES | SURE SUPERVISION - Working Time Fault Delay | 1-2 | 0 - 65000 sec |



• Pressure Alarms Summary

| Data Index | Read & Write | | Data Values | | Limits |
|---------------|-----------------|-------|-------------------------------------|-----|--------|
| | | | re Alarms Summary | | |
| | | Bit 0 | PRESSURE CONTROL - Low Warning | | |
| | | Bit 1 | PRESSURE CONTROL - High Warning | | |
| | | Bit 2 | PRESSURE CONTROL - High Fault | | |
| 79 | R | Bit 3 | PRESSURE CONTROL - Low Fault | 1-2 | - |
| | | Bit 4 | PRESSURE SUPERVISION - Low Warning | | |
| | | Bit 5 | PRESSURE SUPERVISION - High Warning | | |
| | | Bit 6 | PRESSURE SUPERVISION - High Fault | | |
| | | Bit 7 | PRESSURE SUPERVISION - Low Fault | | |

B3.6.3. ProCoat Data

• Common Data

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|--------------------------------------|-------------------|-----------------|
| 926 | R/W | Application Width | 0 | 0.0 - 6000.0 mm |
| 927 | R/W | Setpoint Application Width - Motor 1 | 0 | 0.0 - 6000.0 mm |
| 928 | R/W | Setpoint Application Width - Motor 2 | 0 | 0.0 - 6000.0 mm |
| 929 | R/W | Actual Application Width - Motor 1 | 0 | 0.0 - 6000.0 mm |
| 930 | R/W | Actual Application Width - Motor 2 | 0 | 0.0 - 6000.0 mm |

• Steppers Alarms Summary

| Data Index | Read & Write | | Data Values | Channel Number | Limits |
|---------------|-----------------|-------|---|-------------------|--------|
| | | Stepp | ers Alarms Summary | | |
| | | Bit 0 | STEPPER FAULT – SDO Comm. Motor Left fault | 0 | - |
| 931 | R | Bit 1 | STEPPER FAULT – Gun Motor Left fault | | |
| | | Bit 2 | STEPPER FAULT – SDO Comm. Motor Right fault | | |
| | | Bit 3 | STEPPER FAULT – Gun Motor Right fault | | |



B.3.6.4. Temperature Data

Depending on the number of pumps or the hose-gun outputs of the equipment, the temperature channels will be different. So, in the next table we can see the relationship between the "*Channel Number*" parameter and the temperature channel.

| Channel Number | Temperature Channel | |
|-------------------|---------------------|--|
| 1 | Drum | |
| 11 | Hose 1 | |
| 12 | Hose 2 | |
| | | |
| 20 | Hose 10 | |
| 21 | Gun 1 | |
| 22 | Gun 2 | |
| | | |
| 30 | Gun 10 | |
| 31 | Coating Head Zone 1 | |
| | | |
| 36 | Coating Head Zone 6 | |

> **Example:** Temperature Channels Assignment

For example, if we want to write 100°C in the parameter *"Temperature Set Point"* (Data Index = 115) in the *Drum*, the *Channel Number* parameter has to be equal to 3.

| Data index | Channel number | Read data value |
|------------|----------------|-------------------|
| 115 | 1 | 100 (dec) [100ºC] |

For example, if we want to write 100°C in the parameter *"Temperature Set Point"* (Data Index = 115) in the *Hose 3*, the *Channel Number* parameter has to be equal to 13.

| Data index | Channel number | Read data value |
|------------|----------------|-------------------|
| 115 | 13 | 100 (dec) [100ºC] |



• Temperature Channels Data

| Data Index | Read & Write | Data Values | Channel Number | Limits | |
|---------------|-----------------|---------------------------------------|-------------------|--------------------------|--|
| | | Enable / Disable Temperature Channels | | | |
| 111 | R/W | 0 Disable | 1-36 | 0 - 1 | |
| | | 1 Enable | | | |
| 115 | R/W | Temperature Set Point | 1-36 | 0 - 240 ºC / 32 - 464 ºF | |
| 120 | R | Temperature Actual Value | 1-36 | 0 - 240 ºC / 32 - 464 ºF | |
| 159 | R/W | TEMPERATURE CONTROL PID - Kp | 1-36 | 0 - 130 | |
| 160 | R/W | TEMPERATURE CONTROL PID - Tn | 1-36 | 0 - 130 | |
| 161 | R/W | TEMPERATURE CONTROL PID - Tv | 1-36 | 0 - 80 | |
| 162 | R/W | Temperature Offset | 1-36 | 0 - 200 ºC / 32 - 464 ºF | |
| | 4 R | Temperature Channel Status | | | |
| | | 0 Channel Ready | | | |
| | | 1 Channel Early Ready | | | |
| | | 2 Heat Disabled | | 0.12 | |
| | | 3 Heating | | | |
| 11/ | | 5 High Warning | 1_26 | | |
| 114 | | 6 Low Warning | 1-30 | 0-13 | |
| | | 7 Standby | | | |
| | | 8 High Fault | | | |
| | | 9 Low Fault | | | |
| | | 10 Open Circuit (AAA) or (CCC) | | | |
| | | 12 Shutdown Temperature | | | |
| 360 | R/W | TEMPERATURE CONTROL PID - S | 1-36 | 0-16 | |
| 361 | R/W | TEMPERATURE CONTROL PID - R | 1-36 | 0-30 | |

MUS0650205



Common Data

•

| Data Index | Read & Write | Data Values | Channel Number | Limits |
|---------------|-----------------|-------------------------------------|-------------------|--------------------------|
| | | Temperature Units | | |
| 110 | R/W | 0 Celsius (ºC) | 0 | 0 - 1 |
| | | 1 Fahrenheit (ºF) | | |
| 122 | R/W | Standby Value Zone 1 | 0 | 30 - 100% |
| 123 | R/W | Standby Value Zone 2 | 0 | 30 - 100% |
| 124 | R/W | Standby Value Zone 3 and Zone 4 | 0 | 30 - 100% |
| | | Heating Mode | | |
| 128 | R/W | 0 Sequential | 0 | 0 - 1 |
| | | 1 Simultaneous | | |
| 135 | R/W | Auto-Standby time (0 = DISABLED) | 0 | 0 - 1440 min |
| 136 | R/W | Temperature Low Warning Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 141 | R/W | Temperature Low Fault Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 146 | R/W | Temperature High Warning Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 151 | R/W | Temperature High Fault Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 155 | R/W | Temperature Set Point Minimum Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 198 | R/W | Temperature Set Point Maximum Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 156 | R/W | Temperature Shutdown Value | 0 | 0 - 240 ºC / 32 - 464 ºF |
| 9 | R/W | Waiting Time | 0 | 0 - 300 min |
| 362 | R/W | Temperature Low Fault Delay | 0 | 0 – 6000 Seg |

• Temperature Alarms Summary

| Data Index | Read & Write | | Data Values | | Limits |
|------------|-----------------|-------|--------------------------------|------|--------|
| | | Tempe | erature Alarms Summary | | |
| | | Bit 0 | Not Used | | |
| 157 | | Bit 1 | Temperature Low Warning Value | | |
| | | Bit 2 | Temperature Low Fault Value | 1-36 | |
| | R | Bit 3 | Temperature High Warning Value | | - |
| | | Bit 4 | Temperature High Fault Value | | |
| | | Bit 5 | Shutdown Fault | | |
| | | Bit 6 | Short or Open Circuit Fault | | |
| | | Bit 7 | Not Used | | |



ANNEX C TROUBLESHOOTING

MUS0650205

08/05/2024

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MELTON, S.L. U. - POLIGNO INDUSTRIAL AGUSTINOS CALLE G-34,31160 ORCOYEN, NAVARRA TEL: 00 34 948 321580 Fax: 00 34 948 326584 e-mail: melton@melton.es http://www.meltonhotmelt.com



C.1. ALARMS SCREEN

| FAULT MESSAGE | CAUSES/DESCRIPTION | SOLUTION |
|--|--|---|
| FAULT Drive CAN Communication Error | Lost of communication between drive and PLC | check wiring and connectors |
| | | reboot the equipment |
| FAULT I/O Module Comunication Error | Lost communication between I/O module and PLC | check wiring and connectors |
| | | reboot the equipment |
| FAULT Drive - Motor parameters | the PLC can not write any parameter | cehck the configuration of the motor, |
| writing Error | in the drive of the pump | some parameter is not correct. |
| FAULT CAN SIKO Communication Error | Lost of communication between motor of the gun and PLC | check wiring and connectors |
| | | reboot the equipment |
| FAULT Drive working with Current | the drive of the motor of the pump | check limit current parameter in |
| Limit active | is working over the limit of current | configuration |
| | | Realese pressure. Disacoupling the motor |
| | | and the pump. Try to move the pump |
| | | manually. If you can not, change the |
| | | pump. |
| | | check the temperature programmed of |
| | | platten. Must be higher than softpoint of |
| | | datasheet. |
| | | Check the pressure of the adhesive. Must |
| | | be less than 80 bars. Increase |
| | | check the fan of the motor |
| | | check the fail of the motor. |
| | | check electrical connection of the motor. |
| | | Check the fault in the display of driver. |
| FAULI drive | The drive of the pump is in fault | |
| | | check the connector side of the flexdrum. |
| FALUET Convertex Dermission Dump | The selective connector is onen | If you dont install safety stopped, then |
| | | chock wiring and connectors |
| | The PLC send move order to drive, | check wiring and connectors |
| FAULI Pump Stopped | but it doesn give a feddback to PLC | rabbat the system |
| | | report the system |
| | | change driver |

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| FAULT MESSAGE | CAUSES/DESCRIPTION | SOLUTION |
|----------------------------------|--------------------------------------|---|
| | The pressure of the adhesive is very | check the High limit programmed in |
| | high. ONLY when pressure control is | configuration. |
| FAULT High Pressure in Channel | active | |
| | | In manual mode move the pump and |
| | | make sure than you have flow through |
| | | the gun. Else, check solenoid or module |
| | | the adhesive is cold. Increase |
| | | temperature |
| | | some element is cold. Check temperature |
| | | programmed. |
| | | The PID control is too fast. Decrease the |
| | | Kp parameter |
| | | remove the pressure transducer and |
| | | check it out |
| | The pressure of teh adehsive is too | check the Low limit programmed in |
| | low. ONLY when pressure control is | configuration |
| FAULT Low Pressure in Channel | active | |
| | | check if the pump is rotating |
| | | remove the pressure transducer and |
| | | check it out |
| | | The PID control is too slow. Increse the Kp |
| | | parameter |
| | | check leaked of adhesive in any part of |
| | | the system. |
| | | remove the pressure transducer and |
| | | Check it out |
| Lligh Drossura Foult in Drossura | high ONLY when pressure | check the High limit programmed in |
| Supervision Rump | nigh. ONLY when pressure | comguration. |
| Supervision Pump | | In manual mode move the nump and |
| | | make sure than you have flow through |
| | | the gun. Else, check solenoid or module |
| | | the adhesive is cold. Increase |
| | | temperature |
| | | some element is cold. Check temperature |
| | | programmed. |
| | | remove the pressure transducer and |
| | | check it out |
| | The pressure of the adhesive is too | check the Low limit programmed in |
| Low Pressure Fault in Pressure | low. ONLY when pressure | configuration |
| Supervision Pump 1 | supervision is active | |
| | | check if the pump is rotating |
| | | remove the pressure transducer and |
| | | check it out |
| | | check leaked of adhesive in any part of |
| | | the system. |
| | | remove the pressure transducer and |
| | | check it out |



| FAULT MESSAGE | CAUSES/DESCRIPTION | SOLUTION | |
|---|--|---|--|
| FAULT Motor Procoat | The Siko motor doesnt reach the position desired. | clean the nozzle of the gun. | |
| | | check the position theoretical vs real. | |
| | | make a homming of the motors. | |
| FAULT CAN SDO | | check in configuration the parameter of | |
| COMMUNICATION ERROR (Motor1 ProCoat) | The PLC can't write a parameter in SIKO motor (motor of the gun) | Spindle Pitch, must be 4mm | |
| | | Check the wiring of the motor. | |
| | The heating zone of the platten is | Go to configuration and enable the | |
| FAULT Drum Heating Not Enabled | disabled | chnanel. | |
| FAULT Temperature RTD Sensor Tank | the sensor doesnt show reading | check wiring and connectors | |
| | | change RTD | |
| FAULT Temperature RTD Sensor Hose | the sensor doesnt show reading | check wiring and connectors | |
| | | change RTD | |
| FAULT Temperature RTD Sensor Gun | the sensor doesnt show reading | check wiring and connectors | |
| | | change RTD | |
| FAULT Temperature RTD Sensor Coating Head Zone | the sensor doesnt show reading | check wiring and connectors | |
| | | change RTD | |
| | | check the configuration of high | |
| FAULT High Temperature Tank | the reading of the sensor is too high | temperature limit | |
| | | check wiring and connectors | |
| | | change RTD | |
| | | check the configuration of high | |
| FAULT High temperature Hose | the reading of the sensor is too high | temperature limit | |
| | | check wiring and connectors | |
| | | change hose | |
| FAULT High temperature Coating | | check the configuration of high | |
| Head Zone | the reading of the sensor is too high | temperature limit | |
| | | check wiring and connectors | |
| | | change RTD | |
| | | check the configuration of low | |
| FAULT Low Temperature Tank | the reading of the sensor is too low | temperature limit | |
| | | check wiring and connectors | |
| | | check the fuses of power board | |
| | | check the voltage of the channel | |
| | | check the omhs of the heaters | |

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| FAULT MESSAGE | CAUSES/DESCRIPTION | SOLUTION |
|--------------------------------|--------------------------------------|--|
| | | check the configuration of low |
| FAULT Low Temperature Hose | the reading of the sensor is too low | temperature limit |
| | | check wiring and connectors |
| | | check the fuses of power board |
| | | check the voltage of the channel |
| | | check the omhs of the heaters |
| | | check the configuration of low |
| FAULT Low Temperature Gun | the reading of the sensor is too low | temperature limit |
| | | check wiring and connectors |
| | | check the fuses of power board |
| | | check the voltage of the channel |
| | | check the omhs of the heaters |
| FAULT Low Temperature Coating | | check the configuration of low |
| Head Zone | the reading of the sensor is too low | temperature limit |
| | | check wiring and connectors |
| | | check the fuses of power board |
| | | check the voltage of the channel |
| | | check the omhs of the heaters |
| FAULT Temperature Out of Range | The reading of the sensor is bigger | check the configuration of the rangue in |
| Tank | than the rangue configured | "temperature configuration" |
| | | check wiring and connectors |
| | | change RTD |
| FAULT Temperature Out of Range | The reading of the sensor is bigger | check the configuration of the rangue in |
| Hose | than the rangue configured | "temperature configuration" |
| | | check wiring and connectors |
| | | change hose |
| FAULT Temperature Out of Range | The reading of the sensor is bigger | check the configuration of the rangue in |
| Gun | than the rangue configured | "temperature configuration" |
| | | check wiring and connectors |
| | | change RTD |
| FAULT Temperature Out of Range | The reading of the sensor is bigger | check the configuration of the rangue in |
| Coating Head Zone | than the rangue configured | "temperature configuration" |
| | | check wiring and connectors |
| | | change RTD |
| | Communication lost with Siemens | check ethernet cable |
| FAULT OpcUa Communication | PLC | |
| | | check connectors |
| | | reboot the system |



| FAULT MESSAGE | CAUSES/DESCRIPTION | SOLUTION |
|---|--|---|
| FAULT Temperature over Shutdown Limit | some channel show a temperatire more than 240 | check wiring and connectors |
| | | check voltage of channel |
| | | change RTD |
| Power Board Global Error | the power board send fault to PLC | check wiring and connectors |
| | | reboot system |
| | | change power board |
| Power Board Communication Not Possible - Check wiring or the number of Outputs in "System Designer" Page | the communication between powerboard and PLC is lost | check wiring and connectors |
| | | check configuration of temperature outputs number |



ANNEX D SCREEN CALIBRATION

MUS0650205

08/05/2024

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1. With the equipment turned on, press and hold the screen over an area where there is no button, e.g.

| | Terminal S | ettings | | |
|----------------------------|------------|---------|---|---|
| Connect / Disconnect Timer | | | | |
| Temperature Configuration | | | | |
| Pumps Configuration | | | | _ |
| System Designer | | | Ŧ | |

2. When the following tab appears, click on Show system settings

| Configuration - Pag. 1 | | DT#2024-04-10-10:29:04 | | |
|------------------------|----------------------------|---|----------|--|
| | Terminal S | ettings | * | |
| Cor | Connect / Disconnect Timer | | | |
| Ter | Temperature Configuration | | | |
| Pumps Configuration | | Settings, Project Manager, Update, Logging Show Log at Boot | | |
| | System Designer | | | |
| • User Levels | | | About + | |
| admin | Login | Logout | † | |



3. We will open the system settings. Here, press on Display.

| System Settings | |
|-----------------|--|
| Language | |
| System | |
| Logs | |
| Date & Time | |
| Network | |
| Services | |
| Management | |
| ប៊ីរ ស្ថាវ ទម្ | |

4. To start the calibration process, click on 'Touch screen'.

| MENU | Display Settings | ADMIN C. |
|------------------------------|-------------------|----------|
| Brightness: 10 | | |
| Backlight timeout: always on | | - |
| | Touch calibration | |
| Orientation: | IMH Ĕ | |
| Display Hue: 0 | Restore C | - |



Adhesive Dispensing & Quality Assurance Systems

DESPIECE / PART LIST

FLEXDRUM HF PUMP

R065010208



Adhesive Dispensing & Quality Assurance Systems

| 1. | EQUIPO FLEXDRUM PLATO ALETAS / FLEXDRUM FINNED PLATE EQUIPMENT:2 |
|-------------|--|
| 2. | EQUIPO FLEXDRUM PLATO LISO / FLEXDRUM FLAT PLATE EQUIPMENT: |
| 3. | SUBCONJUNTO BANCADA/ BENCH ASSEMBLY: |
| 4. | SUBCONJUNTO TRAVESAÑO / BUNK ASSEMBLY9 |
| 5. | CONJUNTO EMBOLO PLATO ALETAS / FINNED PLATE PLUNGER ASSEMBLY: 10 |
| 6. | CONJUNTO EMBOLO PLATO LISO / FLAT PLATE PLUNGER ASSEMBLY: |
| 7. | SUBCONJUNTO DISTRIBUIDOR / MANIFOLD ASSEMBLY (900XX722): 16 |
| 8. | CONJUNTO VALVULA PURGA / BLEEDING VALVE ASSEMBLY (916XX998): 17 |
| 9. ASS | SUBCONJUNTO MODULO DE SOPLADO FLEXDRUM V1 / FLEXDRUM BLOWING MODULE SEMBLY V1 (900XX718): |
| 10. ELE | SUBCONJUNTO ELECTROVALVULA MODULO SOPLADO / BLOWING MODULE CTROVALVE ASSEMBLY: |
| 11. | SUBCONJUNTO CARCASA NEUMATICA / NEUMATIC CASE ASSEMBLY: |
| 12. | SUBCONJUNTO REGULADOR / REGULATOR ASSEMBLY: |
| 13. | CONJUNTO VARILLA LLAVE / DRAINVALVE ROD ASSEMBLY: |
| 14. | SUBCONJUNTO SUJECION BIDON / DRUM FIXING ASSEMBLY (904XX214): |
| 15. | SUBCONJUNTO FAJA BIDON / FIBER JACKET ASSEMBLY (900XX689): |
| 16. | SUBCONJUNTO PROTECCION TRASERA / BACK PROTECTION ASSEMBLY (900XX688): 27 |
| 17. (900 | KIT RUEDAS FLEXDRUM / SMARTDRUM / FLEXDRUM / SMARTDRUM WHEEL KIT IXX690): |
| 18. | CONJUNTO ARMARIO FLEXDRUM / FLEXDRUM ELECTRIC CABINET ASSEMBLY: |
| 19. | CONJUNTO NEUMATICO / PNEUMATIC ASSEMBLY: |



1. EQUIPO FLEXDRUM PLATO ALETAS / FLEXDRUM FINNED PLATE EQUIPMENT:





Adhesive Dispensing & Quality Assurance Systems

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---|--|----------|-----|
| 1 | SUBCONJUNTO BANCADA | BENCH ASSEMBLY | PAGE 8 | 1 |
| 2 | SUBCONJUNTO ARMARIO | ELECTRIC CABINET ASSEMBLY | PAGE 29 | 1 |
| 3 | SUBCONJUNTO TRAVESAÑO FLEXDRUM | FLEXDRUM BUNK ASSEMBLY | PAGE 9 | 1 |
| 4 | SUBCONJUNTO EMBOLO PLATO ALETAS | FINNED PLATE PLUNGER ASSEMBLY | PAGE 10 | 1 |
| 5 | CONJUNTO CARCASA NEUMATICA | NEUMATIC CASE ASSEMBLY | PAGE 21 | 1 |
| 6 | SUBCONJUNTO VARILLA LLAVE | DRAIN VALVE ROD ASSEMBLY | PAGE 23 | 1 |
| 7 | SUBCONJUNTO SUJECION BIDON | DRUM FIXING ASSEMBLY | PAGE 24 | 1 |
| 8 | PUENTE FLEXDRUM | FLEXDRUM BRIDGE | - | 1 |
| 9 | CILINDRO NEUMATICO AIRTAC Ø160X1000 | AIRTAC Ø160X1000 PNEUMATIC CYLINDER | 904XX374 | 2 |
| 10 | CASQUILLO VASTAGO CILINDRO AIRTAC | AIRTAC CYLINDER ROD CAP | - | 2 |
| 11 | REDUCCION G3/4 / G3/8 H-BN | G3/4 / G3/8 H-BN REDUCTION | - | 4 |
| 12 | RACOR 90° R3/8 / ER8-P | 90° R3/8 / ER8-P FITTING | - | 2 |
| 13 | RACOR 90° R3/8 / ER10-P | 90° R3/8 / ER10-P FITTING | - | 2 |
| 14 | CUBIERTA TUBOS CILINDRO | CYLINDER TUBES COVER | - | 2 |
| 15 | GUIA TUBO CORRUGADO | CORRUGATED PIPE GUIDE | - | 1 |
| 16 | CUBIERTA GUIA | GUIDE COVER | - | 1 |
| 17 | BARRA DETECCION | DETECTION ROD | - | 1 |
| 18 | CARCASA CANALETA | CHUTE CASING | - | 1 |
| 19 | GUIA BANDEJA | TRAY GUIDE | - | 2 |
| 20 | BANDEJA E-DRUM SIN PROTECCIONES | E-DRUM WITHOUT PROTECTION TARY | - | 1 |
| 21 | MANDO LOBULADO ELESA VCR.372 / 60- 7X7 | LOBED CONTROL ELESA | - | 1 |
| 22 | ABRAZADERA DE CONECTORES CON BRIDA ELESA GN 146-B30-40-2 | GN146 FLANGED CONNECTOR CLAMPS | - | 2 |
| 23 | BRIDA UNITARIA MANGUERA CON VELCRO | UNITARY FLANGE HOSE WITH VELCRO | - | 2 |
| 24 | CHAPA MATRICULA | ID PLATE | - | 1 |
| 25 | REMACHE POP 2.4X8 | RIVETING POP 2,4X8 | - | 6 |
| 26 | TORNILLO ALLEN M5X12 INOX. | STAINLESS M5X12 ALLEN SCREW | - | 1 |
| 27 | TORNILLO ALLEN M8X12 INOX. | STAINLESS M8X12 ALLEN SCREW | - | 4 |
| 28 | TORNILLO ALLEN M16X25 INOX. | STAINLESS M16X25 ALLEN SCREW | - | 6 |
| 29 | TORNILLO GOTA SEBO M6X15 INOX. ISO 7380 | ISO 7380 STAINLESS M6X15 SOCKET BUTTON HEAD SCREW | - | 14 |
| 30 | TORNILLO GOTA SEBO M6X12 INOX. ISO 7380 | ISO 7380 STAINLESS M6X12 SOCKET BUTTON HEAD SCREW | | 1 |
| 31 | TORNILLO GOTA SEBO M8X16 INOX. ISO 7380 | ISO 7380 STAINLESS M8X16 SOCKET BUTTON HEAD SCREW | - | 28 |
| 32 | TORNILLO GOTA SEBO M8X12 INOX. ISO 7380 | ISO 7380 STAINLESS M8X12 SOCKET BUTTON HEAD SCREW | - | 2 |
| 33 | TORNILLO HEXAGONAL M20X40 INOX. | STAINLESS M20X40 HEXAGONAL SCREW | - | 4 |


| 34 | TORNILLO AVELLANADO ALLEN M16X25 INOX | STAINLESS M16X25 COUNTERSUNK SCREW | - | 8 |
|----|--|---|----------|---|
| 35 | TORNILLO AVELLANADO ALLEN M6X12 INOX | STAINLESS M6X12 COUNTERSUNK SCREW | - | 2 |
| 36 | ARANDELA PLANA M5 | STAINLESS M5 FLAT WASHER | - | 1 |
| 37 | ARANDELA GROWER M5 INOX. | STAINLESS Ø5 GROWER WASHER | - | 1 |
| 38 | ARANDELA GROVER 16 INOX. | STAINLESS Ø16 GROWER WASHER | - | 6 |
| 39 | ARANDELA GROVER M20 INOX | STAINLESS Ø20 GROWER WASHER | - | 4 |
| 40 | TUBO POLIURETANO NEGRO 10X7 LONG 935MM | POLYURETHANE BLACK 10X7 PIPE LENGTH 935MM | - | 1 |
| 41 | TUBO POLIUR 8X5.5 AMARILLO LONG 310MM | POLYURETHANE YELLOW 18X5.5 PIPE LENGTH 310MM | - | 1 |
| 42 | TUBO POLIURETANO 10X7 ROJO LONGITUD 1080 MM | POLYURETHANE RED 10X7 PIPE LENGTH 1080MM | - | 2 |
| 43 | TUBO POLIURETANO 10X7 ROJO LONG 1015MM | POLYURETHANE RED 10X7 PIPE LENGTH 1015MM | - | 1 |
| 44 | TUBO POLIURETANO 10X7 AZUL LONGITUD 845 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 845MM | - | 1 |
| 45 | TUBO POLIURETANO 10X7 AZUL LONGITUD 235 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 235MM | - | 2 |
| 46 | MUELLE PROTECCION TUBOS | PIPE PROTECTION SPRING | - | 2 |
| 47 | RECOGEDOR | DUSTPAN | 904XX375 | 1 |

2. EQUIPO FLEXDRUM PLATO LISO / FLEXDRUM FLAT PLATE EQUIPMENT:





| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---|--|---------|-----|
| 1 | SUBCONJUNTO BANCADA | BENCH ASSEMBLY | PAGE 8 | 1 |
| 2 | SUBCONJUNTO ARMARIO | ELECTRIC CABINET ASSEMBLY | PAGE 29 | 1 |
| 3 | SUBCONJUNTO TRAVESAÑO FLEXDRUM | FLEXDRUM BUNK ASSEMBLY | PAGE 9 | 1 |
| 4 | SUBCONJUNTO EMBOLO PLATO LISO | FLAT PLATE PLUNGER ASSEMBLY | PAGE 13 | 1 |
| 5 | CONJUNTO CARCASA NEUMATICA | NEUMATIC CASE ASSEMBLY | PAGE 21 | 1 |
| 6 | SUBCONJUNTO VARILLA LLAVE | DRAIN VALVE ROD ASSEMBLY | PAGE 23 | 1 |
| 7 | SUBCONJUNTO SUJECION BIDON | DRUM FIXING ASSEMBLY | PAGE 24 | 1 |
| 8 | PUENTE FLEXDRUM | FLEXDRUM BRIDGE | - | 1 |
| 9 | CILINDRO NEUMATICO AIRTAC Ø160X1000 | AIRTAC Ø160X1000 PNEUMATIC CYLINDER | - | 2 |
| 10 | CASQUILLO VASTAGO CILINDRO AIRTAC | AIRTAC CYLINDER ROD CAP | - | 2 |
| 11 | REDUCCION G3/4 / G3/8 H-BN | G3/4 / G3/8 H-BN REDUCTION | - | 4 |
| 12 | RACOR 90° R3/8 / ER8-P | 90° R3/8 / ER8-P FITTING | - | 2 |
| 13 | RACOR 90° R3/8 / ER10-P | 90° R3/8 / ER10-P FITTING | - | 2 |
| 14 | CUBIERTA TUBOS CILINDRO | CYLINDER TUBES COVER | - | 2 |
| 15 | GUIA TUBO CORRUGADO | CORRUGATED PIPE GUIDE | - | 1 |
| 16 | CUBIERTA GUIA | GUIDE COVER | - | 1 |
| 17 | BARRA DETECCION | DETECTION ROD | - | 1 |
| 18 | CARCASA CANALETA | CHUTE CASING | - | 1 |
| 19 | GUIA BANDEJA | TRAY GUIDE | - | 2 |
| 20 | BANDEJA E-DRUM SIN PROTECCIONES | E-DRUM WITHOUT PROTECTION TARY | - | 1 |
| 21 | MANDO LOBULADO ELESA VCR.372 / 60- 7X7 | LOBED CONTROL ELESA | - | 1 |
| 22 | ABRAZADERA DE CONECTORES CON BRIDA ELESA GN 146-B30-40-2 | GN146 FLANGED CONNECTOR CLAMPS | - | 2 |
| 23 | BRIDA UNITARIA MANGUERA CON VELCRO | UNITARY FLANGE HOSE WITH VELCRO | - | 2 |
| 24 | CHAPA MATRICULA | ID PLATE | - | 1 |
| 25 | REMACHE POP 2.4X8 | RIVETING POP 2,4X8 | - | 6 |
| 26 | TORNILLO ALLEN M5X12 INOX. | STAINLESS M5X12 ALLEN SCREW | - | 1 |
| 27 | TORNILLO ALLEN M8X12 INOX. | STAINLESS M8X12 ALLEN SCREW | - | 4 |
| 28 | TORNILLO ALLEN M16X25 INOX. | STAINLESS M16X25 ALLEN SCREW | - | 6 |
| 29 | TORNILLO GOTA SEBO M6X12 INOX. ISO 7380 | ISO 7380 STAINLESS M6X12 SOCKET BUTTON HEAD SCREW | | 1 |
| 30 | TORNILLO GOTA SEBO M6X15 INOX. ISO 7380 | ISO 7380 STAINLESS M6X15 SOCKET BUTTON HEAD SCREW | - | 14 |
| 31 | TORNILLO GOTA SEBO M8X12 INOX. ISO 7380 | ISO 7380 STAINLESS M8X12 SOCKET BUTTON HEAD SCREW | - | 2 |
| 32 | TORNILLO GOTA SEBO M8X16 INOX. ISO 7380 | ISO 7380 STAINLESS M8X16 SOCKET BUTTON HEAD SCREW | - | 29 |
| 33 | TORNILLO HEXAGONAL M20X40 INOX. | STAINLESS M20X40 HEXAGONAL SCREW | - | 2 |



| 34 | TORNILLO AVELLANADO ALLEN M6X12 INOX | STAINLESS M6X12 COUNTERSUNK SCREW | - | 2 |
|----|--|---|---|---|
| 35 | TORNILLO AVELLANADO ALLEN M16X25 INOX | STAINLESS M16X25 COUNTERSUNK SCREW | - | 8 |
| 36 | ARANDELA PLANA M5 | STAINLESS M5 FLAT WASHER | - | 1 |
| 37 | ARANDELA GROWER M5 INOX. | STAINLESS Ø5 GROWER WASHER | - | 1 |
| 38 | ARANDELA GROVER 16 INOX. | STAINLESS Ø16 GROWER WASHER | - | 6 |
| 39 | ARANDELA GROVER M20 INOX | STAINLESS Ø20 GROWER WASHER | - | 2 |
| 40 | TUERCA HEXAGONAL M20 INOX. | STAINLESS M20 HEXAGONAL NUT | - | 2 |
| 41 | TUBO POLIURETANO NEGRO 10X7 LONG 935MM | POLYURETHANE BLACK 10X7 PIPE LENGTH 935MM | - | 1 |
| 42 | TUBO POLIUR 8X5.5 AMARILLO LONG 310MM | POLYURETHANE YELLOW 18X5.5 PIPE LENGTH 310MM | - | 1 |
| 43 | TUBO POLIURETANO 10X7 ROJO LONGITUD 1080 MM | POLYURETHANE RED 10X7 PIPE LENGTH 1080MM | - | 2 |
| 44 | TUBO POLIURETANO 10X7 ROJO LONG 1015MM | POLYURETHANE RED 10X7 PIPE LENGTH 1015MM | - | 1 |
| 45 | TUBO POLIURETANO 10X7 AZUL LONGITUD 845 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 845MM | - | 1 |
| 46 | TUBO POLIURETANO 10X7 AZUL LONGITUD 235 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 235MM | - | 2 |
| 47 | MUELE PROTECCION TUBOS | PIPE PROTECTION SPRING | - | 2 |
| 48 | RECOGEDOR | DUSTPAN | - | 1 |

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3. SUBCONJUNTO BANCADA/ BENCH ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---|---|------|-----|
| 1 | BANCADA | BENCH | - | 1 |
| 2 | GUIA SOPORTE BIDON | TANK SUPPORT GUIDE | - | 2 |
| 3 | ABRAZADERA 2 TUBOS Ø10 DIN 72571 | DIN 72571 Ø10 2 PIPE CLAMP | - | 7 |
| 4 | TORNILLO ALLEN M6X12 INOX. | STAINLESS M6X12 ALLEN SCREW | - | 6 |
| 5 | TUERCA DENTADA M4 | M4 TOOTH NUT | - | 7 |
| 6 | PASATABIQUES 90 ER T10 | EQUAL BULKHEAD ELBOW ER10 | - | 6 |
| 7 | RACOR T ER10 / ER10 / ER10-P | T FITTING - TUBE 10 E/R | - | 2 |
| 8 | RACOR 90° M 3/8" BSP - TUBO Ø10 ER | MALE STUD ELBOW M3/8" BSP Ø10 PIPE | - | 1 |
| 9 | RACOR PASATABIQUES ROSCA HEMBRA 3/8" BSP | BULKHEAD FITTING 3/8" BSP | - | 1 |
| 10 | REDUCCION ER8 / ER10 M-P | TUBE 10 / TUBE 8 REDUCER | - | 2 |
| 11 | TUBO POLIURETANO 10X7 AZUL LONGITUD 385 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 385MM | - | 1 |
| 12 | TUBO POLIURETANO 10X7 AZUL LONGITUD 850 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 850MM | - | 1 |
| 13 | TUBO POLIURETANO 10X7 AZUL LONGITUD 375 MM | POLYURETHANE BLUE 10X7 PIPE LENGTH 375MM | - | 1 |
| 14 | TUBO POLIURETANO 10X7 ROJO LONGITUD 785 MM | POLYURETHANE RED 10X7 PIPE LENGTH 785MM | - | 1 |
| 15 | TUBO POLIURETANO 10X7 ROJO | POLYURETHANE RED 10X7 PIPE LENGTH 375MM | - | 2 |



4. SUBCONJUNTO TRAVESAÑO / BUNK ASSEMBLY



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--|------|-----|
| 1 | TRAVESAÑO | BUNK | - | 1 |
| 2 | SOPORTE TUBOS TRAVESAÑO | BULKHEAD TUBE SUPPORT | - | 1 |
| 3 | GUIA MANGUERA | HOSE GUIDE | - | 1 |
| 4 | TORNILLO GOTA SEBO M8X16 INOX. ISO 7380 | ISO 7380 STAINLESS M8X16 SOCKET BUTTON HEAD SCREW | - | 4 |
| 5 | TORNILLO GOTA SEBO M6X10 INOX. ISO 7380 | ISO 7380 STAINLESS M6X10 SOCKET BUTTON HEAD SCREW | - | 2 |
| 6 | ABRAZADERA JIR M40 | JIR M40 CLAMP | - | 2 |



5. CONJUNTO EMBOLO PLATO ALETAS / FINNED PLATE PLUNGER ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--|--------------------|-----|
| 1 | PLATO ALETAS | FINNED PLATE | - | 1 |
| 2 | JUNTA ENCAPSULADA TEFLON 507X30 USA | 507X30 ENCAPSULED TEFLON JOINT | 917XX562 | 2 |
| 3 | BARRA PLATO ALETAS | FINNED PLATE BAR | - | 2 |
| 4 | ARANDELA BARRA | BAR WASHER | - | 2 |
| 5 | SOPORTE MOTOR | MOTOR SUPPORT | - | 1 |
| 6 | MOTORREDUCTOR PLATO | PLATE GEAR MOTOR | - | 1 |
| 7 | ACOPLAMIENTO Ø25.4 - Ø24 | Ø25.4-Ø24 COUPLING | - | 1 |
| 8 | BOMBA ENGRANAJES | GEAR PUMP | DEPENDING MODEL | 1 |
| 9 | SUBCONJUNTO DISTRIBUIDOR | MANIFOLD ASSEMBLY | PAGE 16 | 1 |
| 10 | SUBCONJUNTO MODULO SOPLADO FLEXDRUM V1 | FLEXDRUM BLOWING MODULE ASSEMBLY V1 | PAGE 18 | 1 |
| 11 | SUBC. ELECTROVALVULA MODULO SOPLADO | BLOWING MODULE ELECTRO VALVE ASSEMBLY | PAGE 20 | 1 |
| 12 | TORNILLO ALLEN M3X6 INOX. | STAINLESS M3X6 ALLEN SCREW | - | 2 |
| 13 | TORNILLO ALLEN M4X10 INOX. | STAINLESS M4X10 ALLEN SCREW | - | 1 |
| 14 | TORNILLO ALLEN M4X20 INOX | STAINLESS M4X20 ALLEN SCREW | - | 2 |
| 15 | TORNILLO ALLEN M6X16 INOX | STAINLESS M6X16 ALLEN SCREW | - | 4 |
| 16 | TORNILLO ALLEN M10X35 INOX | STAINLESS M10X35 ALLEN SCREW | - | 4 |
| 17 | TORNILLO ALLEN M10X110 INOX | STAINLESS M10X110 ALLEN SCREW | - | 4 |
| 18 | TORNILLO HEXAGONAL M8X20 INOX | STAINLESS M8X20 HEXAGONAL SCREW | - | 4 |
| 19 | TORNILLO GOTA SEBO M4X6 INOX. ISO 7380 | ISO 7380 STAINLESS M4X6 SOCKET BUTTON HEAD SCREW | - | 6 |
| 20 | TORNILLO GOTA SEBO M5X12 INOX. ISO 7380 | ISO 7380 STAINLESS M5X12 SOCKET BUTTON HEAD SCREW | - | 1 |
| 21 | ESPARRAGO ROSCADO M8X20 INOX. C/PUNTA | THREADED ROD M8X20 SS W/ TIP | - | 6 |
| 22 | TUERCA HEXAGONAL M4 INOX. | STAINLESS M4 HEXAGONAL NUT | - | 12 |
| 23 | ARANDELA GROWER M6 INOX. | STAINLESS M6 GROWER WASHER | - | 4 |
| 24 | ARANDELA GROWER M8 INOX. | STAINLESS M8 GROWER WASHER | - | 4 |
| 25 | ARANDELA GROVER M10 INOX. | STAINLESS M10 GROWER WASHER | - | 4 |
| 26 | ARANDELA PLANA M4 INOX. | STAINLESS M4 FLAT WASHER | - | 12 |
| 27 | ARANDELA DENTADA M3 | TOOTHED M3 WASHER | - | 2 |
| 28 | ARANDELA DENTADA M4 | TOOTHED M4 WASHER | - | 1 |
| 29 | JUNTA TORICA VITON 26X2.5 | VITON O'RING 26X2.5 | 917XX742 | 1 |
| 30 | JUNTA TORICA VITON 40X3 | VITON O'RING 40X3 | - | 1 |
| 31 | JUNTA TORICA VITON 150X2 | VITON O'RING 150X2 | - | 1 |
| 32 | CHAPA ELECTRICA | ELECTRIC SHEET | - | 1 |
| 33 | MUELLE ANTIRETORNO | ANTI-RETURN SPRING | - | 2 |
| 34 | MAZO SONDA | TEMPERATURE PROBE | DEPENDING MODEL | 1 |
| 35 | TOPE SONDA | PROBE LIMITER | - | 1 |
| 36 | ABRAZADERA 1 TUBO Ø15 DIN 72571 | DIN 72571 Ø15 1 TUBE CLAMP | - | 1 |



| 37 | TUBO TEFLON 6X4 LONG 305MM | 6X4 TELON TUBE 305MM LENGTH | - | 1 |
|----|--|------------------------------------|----------|---|
| 38 | TUBO TEFLON 8X6 LONG 318MM | 8X6 TELON TUBE 318MM LENGTH | - | 1 |
| 39 | MAZO TERMOSTATO C/PIPETA | THERMOSTAT HARNESS WITH PIPETTE | 915XX585 | 1 |
| 40 | MAZO VENTILADOR MOTOR BPAIL AUTO BLOW | MOTOR FAN HARNESS | 912XX891 | 1 |
| 41 | MAZO PLATO FLEXDRUM PLATO-CAJA | FLEXDRUM PLATE HARNESS | - | 1 |
| 42 | MAZO MOTOR | MOTOR HARNESS | 912XX890 | 1 |
| 43 | TAPON PIPETA LADO RESISTENCIAS | RESISTANCE SIDE PIPETTE PLUG | - | 6 |

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--------------------|----------|------------|
| 8 | BOMBA ENGRANAJES MODELO MELTON 30CC/REV. | GEAR PUMP 30CC/REV | 916XX266 | 1 |
| 8 | BOMBA ENGRANAJES MODELO MELTON 15CC/REV. | GEAR PUMP 15CC/REV | 918XX174 | 1 |

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|-------------|-------------|----------|-----|
| ~ | SONDA NI120 | NI120 PROBE | 915XX134 | 1 |
| 34 | SONTA PT100 | PT100 PROBE | 917XX147 | 1 |

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6. CONJUNTO EMBOLO PLATO LISO / FLAT PLATE PLUNGER ASSEMBLY:



CONNECTION DETAIL



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--|--------------------|-----|
| 1 | PLATO LISO | FLAT PLATE | - | 1 |
| 2 | JUNTA ENCAPSULADA TEFLON 507X30 USA | 507X30 ENCAPSULED TEFLON JOINT | 917XX562 | 2 |
| 3 | BARRA PLATO ALETAS | FINNED PLATE BAR | - | 2 |
| 4 | ARANDELA BARRA | BAR WASHER | - | 2 |
| 5 | SOPORTE MOTOR | MOTOR SUPPORT | - | 1 |
| 6 | MOTORREDUCTOR PLATO | PLATE GEAR MOTOR | - | 1 |
| 7 | ACOPLAMIENTO Ø25.4 - Ø24 | Ø25.4-Ø24 COUPLING | - | 1 |
| 8 | BOMBA ENGRANAJES | GEAR PUMP | DEPENDING MODEL | 1 |
| 9 | SUBCONJUNTO DISTRIBUIDOR | MANIFOLD ASSEMBLY | PAGE 16 | 1 |
| 10 | SUBCONJUNTO MODULO SOPLADO FLEXDRUM V1 | FLEXDRUM BLOWING MODULE ASSEMBLY V1 | PAGE 18 | 1 |
| 11 | SUBC. ELECTROVALVULA MODULO SOPLADO | BLOWING MODULE ELECTRO VALVE ASSEMBLY | PAGE 20 | 1 |
| 12 | TORNILLO ALLEN M3X6 INOX. | STAINLESS M3X6 ALLEN SCREW | - | 2 |
| 13 | TORNILLO ALLEN M4X10 INOX. | STAINLESS M4X10 ALLEN SCREW | - | 1 |
| 14 | TORNILLO ALLEN M4X20 INOX | STAINLESS M4X20 ALLEN SCREW | - | 2 |
| 15 | TORNILLO ALLEN M6X16 INOX | STAINLESS M6X16 ALLEN SCREW | - | 4 |
| 16 | TORNILLO ALLEN M10X35 INOX | STAINLESS M10X35 ALLEN SCREW | - | 4 |
| 17 | TORNILLO ALLEN M10X90 INOX | STAINLESS M10X90 ALLEN SCREW | - | 4 |
| 18 | TORNILLO HEXAGONAL M8X20 INOX | STAINLESS M8X20 HEXAGONAL SCREW | - | 4 |
| 19 | TORNILLO GOTA SEBO M4X6 INOX. ISO 7380 | ISO 7380 STAINLESS M4X6 SOCKET BUTTON HEAD SCREW | - | 6 |
| 20 | TORNILLO GOTA SEBO M5X12 INOX. ISO 7380 | ISO 7380 STAINLESS M5X12 SOCKET BUTTON HEAD SCREW | - | 1 |
| 21 | ESPARRAGO ROSCADO M8X20 INOX. C/PUNTA | THREADED ROD M8X20 SS W/ TIP | - | 6 |
| 22 | TUERCA HEXAGONAL M4 INOX. | STAINLESS M4 HEXAGONAL NUT | - | 12 |
| 23 | ARANDELA GROWER M6 INOX. | STAINLESS M6 GROWER WASHER | - | 4 |
| 24 | ARANDELA GROWER M8 INOX. | STAINLESS M8 GROWER WASHER | - | 4 |
| 25 | ARANDELA GROVER M10 INOX. | STAINLESS M10 GROWER WASHER | - | 4 |
| 26 | ARANDELA PLANA M4 INOX. | STAINLESS M4 FLAT WASHER | - | 12 |
| 27 | ARANDELA DENTADA M3 | TOOTHED M3 WASHER | - | 2 |
| 28 | ARANDELA DENTADA M4 | TOOTHED M4 WASHER | - | 1 |
| 29 | JUNTA TORICA VITON 26X2.5 | VITON O'RING 26X2.5 | - | 1 |
| 30 | JUNTA TORICA VITON 40X3 | VITON O'RING 40X3 | - | 1 |
| 31 | JUNTA TORICA VITON 150X2 | VITON O'RING 150X2 | - | 1 |
| 32 | CHAPA ELECTRICA | ELECTRIC SHEET | - | 1 |
| 33 | MUELLE ANTIRETORNO | ANTI-RETURN SPRING | - | 2 |
| 34 | MAZO SONDA TEMPERATURA | TEMPERATURE PROBE | - | 1 |
| 35 | TOPE SONDA | PROBE LIMITER | - | 1 |
| 36 | ABRAZADERA 1 TUBO Ø15 DIN 72571 | DIN 72571 Ø15 1 TUBE CLAMP | | 1 |

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| 37 | TUBO TEFLON 6X4 LONG 315MM | 6X4 TELON TUBE 315MM LENGTH | _ | 1 |
|----|--|---------------------------------|----------|---|
| 38 | TUBO TEFLON 8X6 LONG 375MM | 8X6 TELON TUBE 375MM LENGTH | - | 1 |
| 39 | MAZO TERMOSTATO C/PIPETA | THERMOSTAT HARNESS WITH PIPETTE | 915XX585 | 1 |
| 40 | MAZO VENTILADOR MOTOR BPAIL AUTO BLOW | MOTOR FAN HARNESS | 912XX891 | 1 |
| 41 | MAZO PLATO FLEXDRUM PLATO-CAJA | FLEXDRUM PLATE HARNESS | - | 1 |
| 42 | MAZO MOTOR | MOTOR HARNESS | 912XX890 | 1 |
| 43 | DISTANCIAL PLATO LISO | FLAT PLATE DISTANCIAL | - | 2 |
| 44 | TAPON PIPETA LADO RESISTENCIAS | RESISTANCE SIDE PIPETTE PLUG | - | 6 |
| | | | | |

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--------------------|----------|-----|
| 8 | BOMBA ENGRANAJES MODELO MELTON 30CC/REV. | GEAR PUMP 30CC/REV | 916XX266 | 1 |
| 8 | BOMBA ENGRANAJES MODELO MELTON 15CC/REV. | GEAR PUMP 15CC/REV | 918XX174 | 1 |

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|-------------|-------------|----------|-----|
| | SONDA NI120 | NI120 PROBE | 915XX134 | 1 |
| 34 | SONTA PT100 | PT100 PROBE | 917XX147 | 1 |

7. SUBCONJUNTO DISTRIBUIDOR / MANIFOLD ASSEMBLY (900XX722):



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|------------------------------------|----------|-----|
| 1 | CUERPO DISTRIBUIDOR | MANIFOLD BODY | - | 1 |
| 2 | PLACA INTERMEDIA BOMBA-DISTRIBUIDOR | MANIFOLD – PUMP INTERMEDIATE PLATE | - | 1 |
| 3 | SUBCONJUNTO VALVULA DE PURGA | BLEEDING VALVE ASSEMBLY | PAGE 17 | 1 |
| 4 | TAPON M30X1.5 CON JUNTA | M30x1.5 PLUG WITH SEAL | 911XX428 | 2 |
| 5 | JUNTA TORICA VITON 26X2.5 | 26X2.5 VITON O-RING | 917XX742 | 2 |
| 6 | JUNTA TORICA VITON 17X2 | 17X2 VITON O-RING | 910XX500 | 1 |
| 7 | TORNILLO ALLEN M5X20 INOX. | STAINLESS M5X20 ALLEN SCREW | - | 3 |
| 8 | TORNILLO ALLEN M10X20 INOX. | STAINLESS M10X20 ALLEN SCREW | - | 4 |
| 9 | KIT REGULADOR DE PRESION TARADO A 80BAR V1 | PRESSURE REGULATOR 80 BAR V1 | 912XX169 | 1 |
| 10 | TAPON CAB HEXAGONAL 7/8 14H UNF | 7/8 14H UNF HEXAGONAL PLUG | 799XX146 | 2 |
| 11 | HELICOIL M10X15 | M10X15 HELICOIL | - | 4 |
| 12 | HELICOIL M5X7.5 | M5X7,5 HELICOIL | - | 3 |



8. CONJUNTO VALVULA PURGA / BLEEDING VALVE ASSEMBLY (916XX998):



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---------------------------|-----------------------------|----------|-----|
| 1 | CUERPO VALVULA PURGA | BLEED VALVE BODY | - | 1 |
| 2 | TAPA VALVULA PURGA | BLEED VALVE LID | - | 1 |
| 3 | AGUJA VALVULA PURGA | BLEED VALVE NOZZLE | 918XX540 | 1 |
| 4 | TORNILLO ALLEN M5X20 INOX | STAINLESS M5X20 ALLEM SCREW | - | 3 |
| 5 | PASADOR CILINDRICO 4X12 | 4X12 CYLINDER PIN | - | 2 |



9. SUBCONJUNTO MODULO DE SOPLADO FLEXDRUM V1 / FLEXDRUM BLOWING MODULE ASSEMBLY V1 (900XX718):





| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---|--|----------|-----|
| 1 | CUERPO MODULO ALTO CAUDAL | HIGH FLOW BODY MODULE | - | 1 |
| 2 | BASE MODULO SOPLADO | BLOW MODULE BASE | - | 1 |
| 3 | ADAPTADOR MODULO SOPLADO | BLOW MODULE ADAPTER | - | 1 |
| 4 | AGUJA MODULO CP. | NEEDLE MODULE CP | - | 1 |
| 5 | PLATILLO EMBOLO ALTO CAUDAL | HIGH FLOW PISTON PLATE | - | 2 |
| 6 | JUNTA EMBOLO ALTO CAUDAL | HIGH FLOW PISTON JOINT | 915XX764 | 1 |
| 7 | TUERCA EMBOLO | NEEDLE NUT | - | 1 |
| 8 | CONJUNTO CASQUILLO JUNTAS | CAP SEALS ASSEMBLY | - | 1 |
| 9 | MUELLE SPEC C0420-063-1000-S | C0420-063-1000-S SPEC SPRING | - | 1 |
| 10 | MUELLE MODULO INFERIOR | INFERIOR MODULE CO SPRING | - | 1 |
| 11 | LENTEJUELA BOLA 7 | BUSHING BALL 7 | - | 1 |
| 12 | TORNILLO ALLEN M4X12 INOX | STAINLESS M4X12 ALLEN SCREW | - | 4 |
| 13 | TORNILLO ALLEN M5X40 INOX. | STAINLESS M5X40 ALLEN SCREW | - | 2 |
| 14 | TORNILLO AVELLANADO ALLEN M4X12 INOX. | STAINLESS M4X12 ALLEN COUNTERSUNK SCREW | - | 4 |
| 15 | ARANDELA GROWER M4 INOX. | STAINLESS M4 GROWER WASHER | - | 5 |
| 16 | JUNTA TORICA VITON 7,65X1,78 | VITON O'RING 7,65X1,78 | 910XX324 | 2 |
| 17 | JUNTA TORICA VITON 12X1 | VITON O'RING 12X1 | 919XX465 | 1 |
| 18 | JUNTA TORICA VITON 13X2 | VITON O'RING 13X2 | - | 2 |
| 19 | JUNTA TORICA VITON 16X2 | VITON O'RING 16X2 | 914XX082 | 1 |
| 20 | ANILLO ELASTICO EJE 15 | 15 AXIS ELASTIC RING | 915XX632 | 1 |
| 21 | RACOR 90° NIQUELADO M 1/4" BSP – TUBO Ø6ER | M 1/4" BSP – Ø6ER 90° FITTING | - | 1 |
| 22 | RACOR 90° NIQUELADO M 1/4" BSP – TUBO Ø8ER | M 1/4" BSP – Ø8ER 90° FITTING | - | 1 |
| 23 | CULATA MODULO SOPLADO V1 | BLOWING MODULE HEAD V1 | - | 1 |
| 24 | PUNTA TUBO MODULO SOPLADO V1 | BLOWING MODULE PIPE TIP V1 | - | 1 |
| 25 | TUBO MODULO SOPLADO FLEXDRUM V1 | FLEXDRUM BLOWING MODULE PIPE V1 | - | 1 |
| 26 | KIT PUNTA AGUJA MODULO SOPLADO FLEXDRUM V1 | FLEXDRUM BLOWING MODULE NEEDLE TIP KIT V1 | - | 1 |



10. SUBCONJUNTO ELECTROVALVULA MODULO SOPLADO / BLOWING MODULE ELECTROVALVE ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|-----------------------------------|--------------------------------------|----------|-----|
| 1 | ELECTROVALVULA 3/2 - 1/8 - 24V DC | 3/2-1/8-24V DC SOLENOID ELECTROVALVE | 917XX285 | 1 |
| 2 | SILENCIADOR CORTO 1/8"GAS | 1/8" GAS SHORT SILENCER | - | 1 |
| 3 | REGULADOR DE PRESION EN LINEA | PRESSURE REGULATOR IN LINE | - | 1 |
| 4 | RACOR 90° G1/4 TUBO Ø8 ER | 90° FITTING G1/4 / ER8-P | - | 2 |
| 5 | RACOR 90° R1/4 / R1/4 - B | 90° FITTING R1/4 / R1/4-B | - | 1 |
| 6 | RACOR RECTO R1/8 / R1/4-B | STRAIGHT FITTING R1/8 / R1/4-B | - | 1 |
| 7 | T IGUAL HEMBRA 1/4" BSP | T FITTING 1/4" BSP BRASS | - | 1 |
| 8 | RACOR 90° G1/8 / ER6-P | FITTING 90° G1/8M / ER6-P | - | 1 |
| 9 | RACOR ALARGADOR M-H 1/4G-1/4G SMC | M-F 1/4G-1/4G SMC EXTENSION FITTING | - | 1 |



11.SUBCONJUNTO CARCASA NEUMATICA / NEUMATIC CASE ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|-------------------------------------|------------------------|----------|-----|
| 1 | CARCASA NEUMATICA | NEUMATIC CASE | - | 1 |
| 2 | CIERRE DE 1/4 VUELTA CON HEXAGONO 8 | CASE CLOSURE SYSTEM | | 1 |
| 3 | LENGÜETA DE CIERRE | CLOSING CATCH | 900XX189 | 1 |
| 4 | SUBCONJUNTO REGULADOR | REGULATOR ASSEMBLY | PAGE 22 | 1 |
| 5 | BISAGRA ESSENTRA 395634E | 395634E ESSENTRA HINGE | - | 2 |
| 6 | TUERCA DENTADA M5 | M5 NUT FLANGE | - | 4 |



12. SUBCONJUNTO REGULADOR / REGULATOR ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--|----------|-----|
| 1 | REGULADOR SMC - ARG20-F02G1H | SMC ARG20-F02G3H PRESSURE REGULATOR | 913XX103 | 1 |
| 2 | RACOR T ER10 / G1/4 / ER10 P | T FITTING ER10 7 G1/4 ER10 P | - | 1 |
| 3 | T DOBLE HEMBRA LATERAL H1/4 CENTRAL M1/4 | H1/4G LATERAL FEMALE DOUBLE T FITTING | - | 1 |
| 4 | RACOR RECTO G1/4 / ER10-P | G1/4 Ø10TUBE STRAIGHT FITTING | - | 1 |
| 5 | VALVULA ANTIRRETORNO SMC AKH08A-02S | BACKSTOPS VALVE SMC | 911XX756 | 1 |
| 6 | REDUCCION ER8 / ER10 M-P | TUBE 10 / TUBE 8 REDUCER | - | 1 |
| 7 | TUBO POLIURETANO 8X5,5 AMARILLO LONG 160MM | POLYURETHANE YELLOW 8X5.5 PIPE LENGTH 160MM | - | 1 |
| 8 | TUBO POLIURETANO NEGRO 10X7 LONG 270MM | POLYURETHANE BLACK 10X7 PIPE | - | 1 |



13. CONJUNTO VARILLA LLAVE / DRAINVALVE ROD ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|-------------------------------------|--------------|------|-----|
| 1 | VARILLA LLAVE | KEY ROD | - | 1 |
| 2 | CASQUILLO VARILLA | ROD BUSHING | - | 1 |
| 3 | ESPARRAGO ROSCADO M4X6 C/PUNTA INOX | PLUG M4X6 BO | - | 2 |



14. SUBCONJUNTO SUJECION BIDON / DRUM FIXING ASSEMBLY (904XX214):



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|------------------------------|------------------------------|------|-----|
| 1 | SUJECION BIDON | DRUM FIXING | - | 1 |
| 2 | PUERTA SUJECION BIDON | DRUM FIXING DOOR | - | 2 |
| 3 | BRIDA CIERRE GN851.3-320-T | GN851.3-320-T CLOSURE BRIDLE | | 1 |
| 4 | UÑA DE LA BRIDA CIERRE | CLOSURE BRIDLE NAIL | - | 1 |
| 5 | ARANDELA GROWER M6 INOX. | STAINLESS M6 GROWER WASHER | - | 6 |
| 6 | TORNILLO ALLEN M6X10 INOX. | STAINLESS M6X10 ALLEN SCREW | - | 6 |
| 7 | NUT FLANGE M6 ZINC | NUT FLANGE M6 ZINC | - | 4 |
| 8 | PEGATINA TEMPERATURA | TEMPERATURE STICKER | - | 1 |
| 9 | PEGATINA ATRAPAMIENTO | ENTRAPMENT STICKER | - | 1 |
| 10 | PEGATINA GUANTES | GLOVES STICKER | - | 1 |
| 11 | PEGATINA BOTAS | BOTES STICKER | - | 1 |
| 12 | PEGATINA CARETA | MASK STICKER | - | 1 |
| 13 | PEGATINA TRAJE | SUIT STICKER | - | 1 |
| 14 | HORQUILLA GN 951.1-M6-32-110 | GN 951.1-M6-32-110 FORK | - | 1 |

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| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|---|------|-----|
| 1 | FAJA BIDON | BELT DRUM | - | 1 |
| 2 | PUERTA INFERIOR FAJA | BELT BOTTOM DOOR | - | 2 |
| 3 | PUERTA SUPERIOR FAJA | UPPER BOTTOM DOOR | - | 2 |
| 4 | PEGATINA TEMPERATURA | TEMPERATURE RISK STICKER | - | 1 |
| 5 | PEGATINA ATRAPAMIENTO | ENTRAPMENT RISK STICKER | - | 1 |
| 6 | PEGATINA CARETA | MASK STICKER | - | 1 |
| 7 | PEGATINA TRAJE | SUIT STICKER | - | 1 |
| 8 | PEGATINA GUANTES | GLOVE STICKER | - | 1 |
| 9 | PEGATINA BOTAS | BOOT STICKER | - | 1 |
| 10 | ASA GRANDE NEGRA | BLACK BIG HANDLE | - | 2 |
| 11 | TORNILLO ALLEN M8X16 INOX. | STAINLESS M8X16 ALLEN SCREW | - | 4 |
| 12 | TORNILLO ALLEN M6X10 INOX. | STAINLESS M6X10 ALLEN SCREW | - | 30 |
| 13 | TORNILLO ALLEN M4X12 INOX | STAINLESS M4X12 ALLEN SCREW | - | 4 |
| 14 | ARANDELA GROWER M6 INOX | STAINLESS M6 GROVER WASHER | - | 30 |
| 15 | ARANDELA GROWER M8 INOX. | STAINLESS M8 GROWER WASHER | - | 4 |
| 16 | NUT FLANGE M6 ZINC | ZINC M6 NUT FLANGE | - | 24 |
| 17 | ABRAZADERA 1 TUBO Ø8 DIN 72571 | DIN 72571 Ø8 1 TUBE CLAMP | - | 3 |
| 18 | REMACHE 4.8X9.5 CABEZA NEGRA | RIVETING POP 4.8X9.5 BLACK HEAD | - | 3 |
| 19 | TUBO POLIURETANO 8X5.5 NEGRO LONGITUD 420MM | POLYURETHANE BLACK 8X5.5 PIPE LENGTH 420MM | - | 1 |
| 20 | MAZO INTERRUPTOR MAGNETICO FAJA | MAGNETIC SWITCH HARNESS | - | 1 |
| 21 | BRIDA CIERRE GN851.3-320-T | GN851.3-320-T CLOSURE BRIDLE | | 5 |
| 22 | UÑA DE LA BRIDA CIERRE | CLOSURE BRIDLE NAIL | - | 5 |
| 23 | HORQUILLA GN 951.1-M6-32-78 | GN 951.1-M6-32-78 FORK | - | 1 |
| 24 | HORQUILLA GN 951.1-M6-32-130 | GN 951.1-M6-32-130 FORK | - | 4 |
| 25 | CONO POSICION CHAPAS LATERALES | M65 LATERAL SHEETS POSITIONER CONE | - | 2 |



16. SUBCONJUNTO PROTECCION TRASERA / BACK PROTECTION ASSEMBLY (900XX688):



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|--|------|-----|
| 1 | PROTECCION TRASERA | BACK PROTECTION | - | 1 |
| 2 | PUERTA SUPERIOR FAJA | UPPER BELT DOOR | - | 2 |
| 3 | BRIDA CIERRE GN851.3-320-T | GN851.3-320-T CLOSURE BRIDLE | | 1 |
| 4 | UÑA DE LA BRIDA CIERRE | CLOSURE BRIDLE NAIL | - | 1 |
| 5 | MAZO INTERRUPTOR MAGNETICO FAJA | BELT MAGNETIC SWITCH HARNESS | - | 1 |
| 6 | TUBO POLIURETANO 8X5,5 NEGRO LONGITUD 420MM | BLACK 8X5,5 POLIURETANE TUBE LENGTH 420MM | - | 1 |
| 7 | ABRAZADERA 1 TUBO Ø8 DIN 72571 | DIN 72571 Ø8 1 TUBE CLAMP | - | 3 |
| 8 | ARANDELA GROWER M6 INOX. | STAINLESS M6 GROWER WASHER | - | 6 |
| 9 | TORNILLO ALLEN M6X10 | STAINLESS M6X10 ALLEN SCREW | - | 6 |
| 10 | TORNILLO ALLEN M4X12 | STAINLESS M4X12 ALLEN SCREW | _ | 4 |
| 11 | NUT FLANGE M6 ZINC | NUT FLANGE M6 ZINC | - | 6 |
| 12 | REMACHE 4.8X9,5 CABEZA NEGRA | RIVETING POP 4.8X9.5 BLACK HEAD | - | 3 |
| 13 | TORNILLO GOTA SEBO M8X16 INOX ISO 7380 | ISO 7380 STAINLESS M8X16 SOCKET BUTTON HEAD SCREW | - | 6 |
| 14 | PEGATINA TEMPERATURA | TEMPERATURE RISK STICKER | - | 1 |
| 15 | PEGATINA ATRAPAMIENTO | ENTRAPMENT RISK STICKER | - | 1 |
| 16 | PEGATINA CARETA | MASK STICKER | - | 1 |
| 17 | PEGATINA BOTAS | BOOT STICKER | - | 1 |
| 18 | PEGATINA TRAJE | SUIT STICKER | - | 1 |
| 19 | PEGATINA GUANTES | GLOVE STICKER | - | 1 |
| 20 | HORQUILLA GN 951.1-M6-32-78 | GN 951.1-M6-32-78 FORK | - | 1 |
| 21 | CONO POSICION CHAPAS LATERALES | M65 LATERAL SHEETS POSITIONER CONE | - | 2 |



17. KIT RUEDAS FLEXDRUM / SMARTDRUM / FLEXDRUM / SMARTDRUM WHEEL KIT (900XX690):



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|---------------------------|--------------------------------------|----------|-----|
| 1 | RUEDA MOVIL SERIE PESADA | SWIVEL WHEEL HEAVY SERIES WITH BRAKE | 914XX620 | 2 |
| 2 | RUEDA FIJA SERIE PESADA | FIXED WHEEL HEAVY SERIES WITH BRAKE | 914XX619 | 2 |
| 3 | TORNILLO HEXAGONAL M10X16 | M10X16 STAINLESS HEXAGONAL SCREW | - | 16 |
| 4 | ARANDELA GROVER M10 INOX. | STAINLESS M10 GROVER WASHER | | 8 |



18. CONJUNTO ARMARIO FLEXDRUM / FLEXDRUM ELECTRIC CABINET ASSEMBLY:

| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--|-----------------------------------|----------|-----|
| 1 | PANTALLA ESMART 107 7" | ESMART 107 7" POWERPANEL | 918XX710 | 1 |
| 2 | INTERRUPTOR SOPLADO | BLOWING SWITCH | 913XX482 | 1 |
| 3 | INTERRUPTOR MANUAL GENERAL III 63A S/ACC | MAIN SWITCH III 63A S/ACC | - | 1 |
| 4 | VARIADOR MS300 | MS300 INVERTER | 918XX709 | 1 |
| 5 | PCB ASSY 12Z GEAR-PUMP NI-120 | PCB ASSY 12Z GEAR-PUMP NI-120 | 151XX680 | 1 |
| 6 | PCB ASSY UPDATED SATC 4 ZONE | PCB ASSY UPDATED SATC 4 ZONE | 911XX875 | 2 |
| 7 | FUENTE ALIMENTACION 230VAC-24VDC 240W-34 | POWER SUPPLY 230VAC-24VDC 240W-34 | 900XX716 | 1 |
| 8 | CONTACTOR III 43A-BOBINA 24VDC | III CONTACTOR 43A- 24VDC COIL | 914XX637 | 1 |
| 9 | RELE ESTADO SOLIDO GRD 22.5 20A | SOLID STATE RELAY GRD 22.5 20A | 910XX791 | 3 |
| 10 | RELE SEGURIDAD BIMANUAL 24VDC | 24VDC BIMANUAL SECURITY RELAY | - | 1 |
| 11 | MODULO CAN OPEN 8DI/DO 24VDC | 24VDC 8DI/DO CAN OPEN MODULE | 904XX450 | 1 |
| 12 | BALIZA LED AMBAR FIJA 24VDC | 24VDC AMBER LED BEACON | 913XX484 | 1 |

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19. CONJUNTO NEUMATICO / PNEUMATIC ASSEMBLY:



| N.º | DESCRIPCIÓN | DESCRIPTION | REF. | QTY |
|-----|--------------------------------------|-----------------------------------|----------|-----|
| 1 | FILTRO AF20-F02B | AF20-F02B G1/4" FILTER | 914XX876 | 1 |
| 2 | ELECTROVALVULA 5/3 CC SY7320-5DZ | SOLENOID 5/3 DE CC 0,4W 24VDC 1/4 | 913XX440 | 1 |
| 3 | RACOR RECTO R1/4 / R1/4-B | STRAIGHT FITTING R1/4 / R1/4-B | - | 1 |
| 4 | SILENCIADOR CORTO G1/8-BN | SILENCER G1/8-BN | - | 2 |
| 5 | RACOR 90° G1/4 / ER10-P | 90° FITTING G1/4 / ER10-P | - | 1 |
| 6 | T HEMBRA MACHO LATERAL 1/4 METALICO | FEMALE T 1/4 | - | 1 |
| 7 | RACOR 90° G1/4 / ER8-P | 90° FITTING G1/4 / ER8-P | - | 1 |
| 8 | REGUL. CAUDAL 1/4 / ER10-P TORN. OC. | 1/4 / ER10-P FLOW REGULATOR | - | 1 |
| 9 | RACOR RECTO G1/4 / ER10-P | STRAIGHT FITTING G1/4 / ER10-P | - | 1 |



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S065160203 FLEXDRUM 1 PUMP 2-6 NI120

| | | | К | 15/04/2024 | oelizalde | PM21644 Change level sensors | REVISION |
|--------------|---|--|---|------------|-----------|---------------------------------------|----------|
| | ValcoMelton, S.L.U. | COVER PAGE | J | 04/04/2024 | oelizalde | PM21644 Change level sensors | K |
| | European Headquarters Pol.Ind. Agustinos C/G D34 | | Ι | 11/03/2024 | imateo | PM21717 Change touch sreen connection | |
| VALCO MELTON | 31160 Orcoyen, Navarra, Spain | | Н | 21/12/2023 | oelizalde | PM21656 Change connector pinout | SCHEME |
| | Tel: +34 948 321 585 Fax: +34 948 326 584 | PROJECT: COCESCODOD EL EVEDELIMA E DUME DI CINITAD | G | 23/11/2023 | oelizalde | PM21656 Change connector pinout | 01 |
| | | S065160203 FLEXDROM 1 POMP 2-6 NI120 | | DATE | NAME | CHANGES | |

| 1-Document book | | | | | | | | | | | |
|---|----------|----------|----------|-------------|------------------------|---------------------|--|--|--|--------------------------------|----|
| Drawing | Function | Location | Revisio | n Date | Created by | Description | | | | Folder designation | |
| 01 | F1 | P1 | к | 15/04/2024 | oelizalde | Cover page | | | | | |
| 02 | F1 | P1 | к | 15/04/2024 | oelizalde | Drawing list | | | | | |
| 03 | F1 | P1 | к | 15/04/2024 | oelizalde | Drawing list | | | | | |
| 04 | F1 | P1 | к | 15/04/2024 | oelizalde | Wiring line diagram | | | | | |
| 05 | F1 | P1 | к | 15/04/2024 | oelizalde | SERVICE WIRES | | | | | |
| 06 | F1 | P1 | к | 15/04/2024 | oelizalde | POWER SUPPLY | | | | | |
| 07 | F1 | P1 | к | 15/04/2024 | oelizalde | CHANNELS 1 AND 2 | | | | | |
| 08 | F1 | P1 | к | 15/04/2024 | oelizalde | CHANNELS 3 AND 4 HP | | | | | |
| 09 | F1 | P1 | к | 15/04/2024 | oelizalde | CHANNELS 5 AND 6 HP | | | | | |
| 10 | F1 | P1 | к | 15/04/2024 | oelizalde | DRUM HEATERS | | | | | |
| 11 | F1 | P1 | к | 15/04/2024 | oelizalde | TOUCH SCREEN | | | | | |
| 12 | F1 | P1 | к | 15/04/2024 | oelizalde | MOTOR 1 | | | | | |
| 13 | F1 | P1 | к | 15/04/2024 | oelizalde | OUTPUTS/INPUTS | | | | | |
| 14 | F1 | P1 | к | 15/04/2024 | oelizalde | MODULE DI/DO | | | | | |
| 15 | F1 | P1 | к | 15/04/2024 | oelizalde | BIMANUAL RELAY | | | | | |
| 16 | F1 | P1 | к | 15/04/2024 | oelizalde | COMMUNICATION | | | | | |
| 17 | F1 | P1 | к | 15/04/2024 | oelizalde | GUN MOTORS | | | | | |
| 18 | F1 | P1 | к | 15/04/2024 | oelizalde | PNEUMATIC | | | | | |
| 19 | F1 | P1 | к | 15/04/2024 | oelizalde | Electrical cabinet | | | | | |
| 20 | F1 | P2 | к | 15/04/2024 | oelizalde | Electrical box | | | | | |
| 21 | F1 | P1 | к | 15/04/2024 | oelizalde | XA-(1/1) | | | | | |
| 22 | F1 | P1 | к | 15/04/2024 | oelizalde | XPE-(1/1) | | | | | |
| 23 | F1 | P1 | к | 15/04/2024 | oelizalde | XCS-XN | | | | | |
| 24 | F1 | P1 | к | 15/04/2024 | oelizalde | XCC-(1/2) | | | | | |
| 25 | F1 | P1 | к | 15/04/2024 | oelizalde | XCC-(2/2) | | | | | |
| 26 | F1 | P1 | к | 15/04/2024 | oelizalde | XV-(1/1) | | | | | |
| 27 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 28 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 29 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 30 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 31 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 32 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| 33 | F1 | P1 | к | 15/04/2024 | oelizalde | Bill of materials | | | | | |
| ValcoMelton, S.L.U. European Headquarters Pol.Ind. Agustinos C/G D34 31160 Orcoyen, Navarra, Spain Tel: +34 948 321 585 | | | PROJECT. | Drawing lis | t | K J I H | 15/04/2024 04/04/2024 11/03/2024 21/12/2023 23/11/2023 | oelizalde oelizalde imateo oelizalde oelizalde | PM21644 Change level sensors PM21644 Change level sensors PM21717 Change touch sreen connect PM21656 Change connector pinout PM21656 Change connector pinout | TEVIS REVIS tion SCHE | |
| Fdx. +34 948 320 384 | | | | S065160203 | FLEXDRUM 1 PUMP 2-6 NI | 20 | DEV/ | DATE | NAME | CHANGES | 02 |

REV.

DATE

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| VALCO MELTON | ValcoMelton, S.L.U. European Headquarters Pol.Ind. Agustinos C/G D34 31160 Orcoyen, Navarra, Spain Tel: +34 948 321 585 Fax: +34 948 326 584 | ELECTRICAL BOX | | К | 15/04/2024 | oelizalde | PM21644 Change level sensors | SCALE |
|--------------|---|---------------------|---------------------------|------|------------|-----------|---------------------------------------|----------|
| | | | | J | 04/04/2024 | oelizalde | PM21644 Change level sensors | 1/2 |
| | | CONNECTION | | I | 11/03/2024 | imateo | PM21717 Change touch sreen connection | REVISION |
| | | CONNECTION | | н | 21/12/2023 | oelizalde | PM21656 Change connector pinout | K |
| | | PROJECT: S065160203 | FLEXDRUM 1 PUMP 2-6 NI120 | G | 23/11/2023 | oelizalde | PM21656 Change connector pinout | DRAWING |
| | | | | REV. | DATE | NAME | CHANGES | 20 |